

COMSOL Conference 2015 Boston

Session: Computational Fluid Dynamics

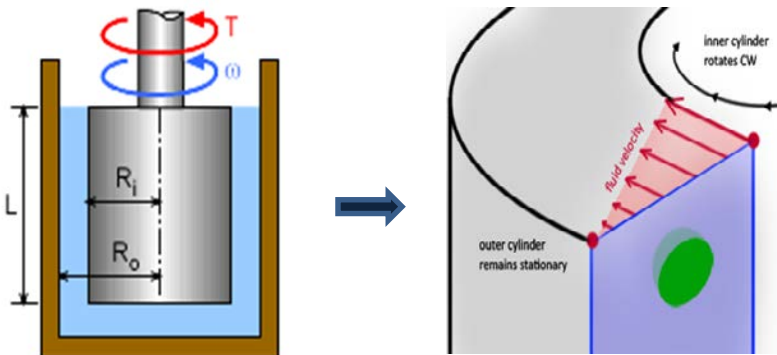
Boston Marriot Newton Charles River West

Boston, MA

1:00 pm-2:45 pm

October 8th, 2015.

Fluid Motion Between Rotating Concentric Cylinders Using COMSOL MultiphysicsTM



Kabita Barman
Sravanthi Mothupally
Archana Sonejee
Patrick L.Mills*



Department of Chemical and Natural Gas Engineering

Texas A & M University-Kingsville

Kingsville-TX 78363-8202 USA

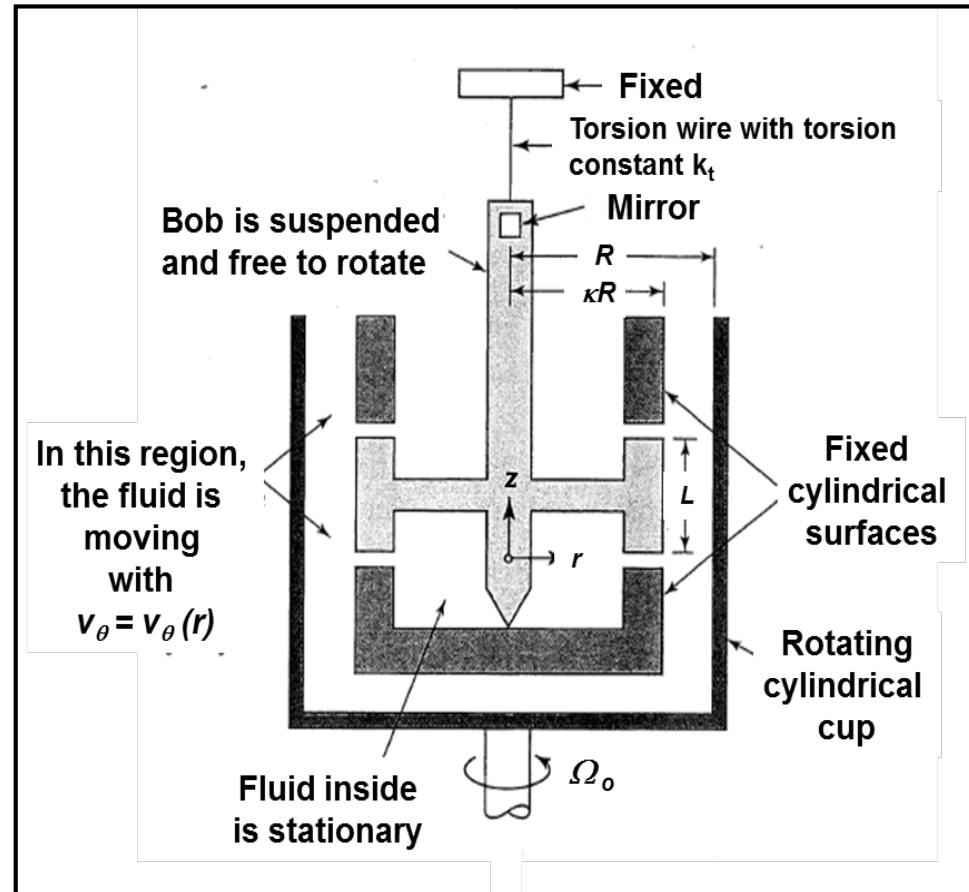
***Patrick.Mills@tamuk.edu**

**COMSOL
CONFERENCE
2015 BOSTON**

Outline

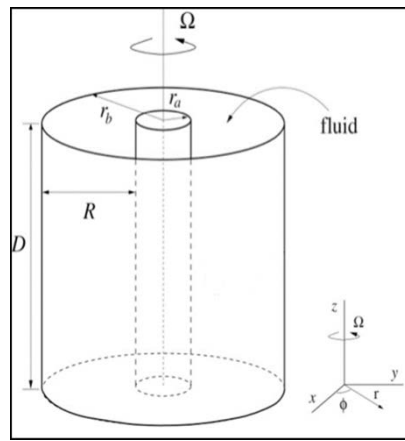
- Introduction
- Historical Background
- Applications
- Governing Equations
- Results and Discussion
- Computational Challenges
- Key Observations

Couette Viscometer



Introduction

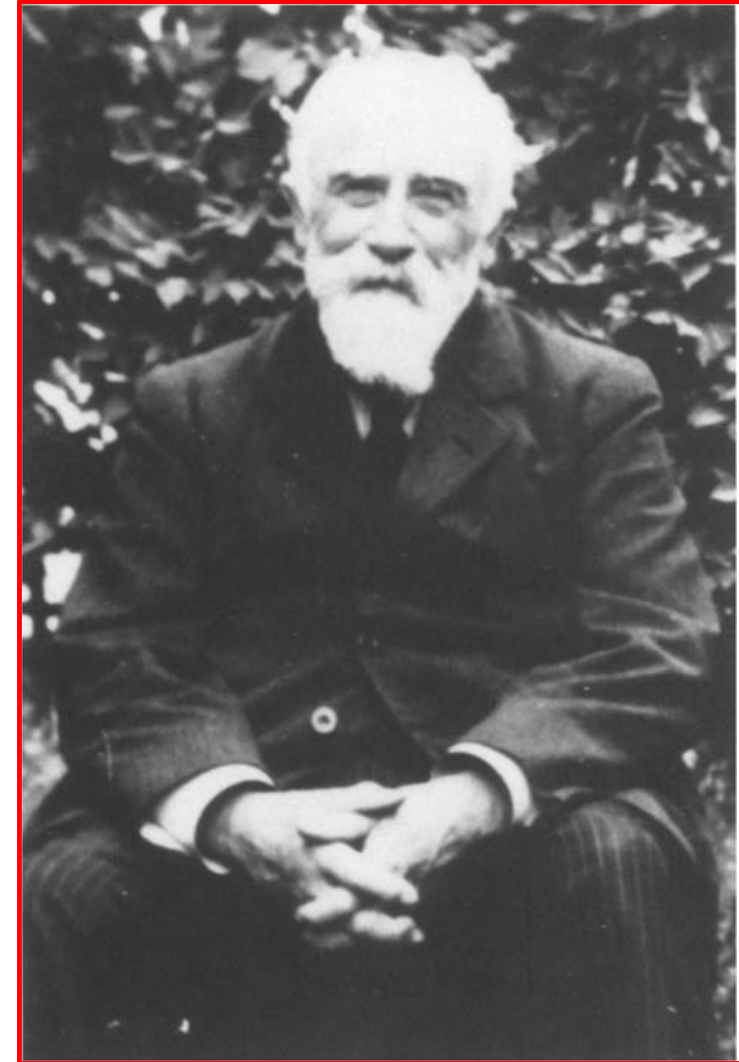
- Fluid flow patterns contained between two concentric rotating cylinders has received noticeable attention in various fields of study.
- One widely used application of this system is the *rotational viscometer*. This study focuses on the analysis of CFD of a Newtonian incompressible fluid in the annular gap for the case where non-ideal end effects are included using COMSOL Multiphysics™.
- The torque behavior imparted by fluid on the inner cylinder is evaluated to better understand non ideal fluid behavior.



Monitoring and Control
Laboratories

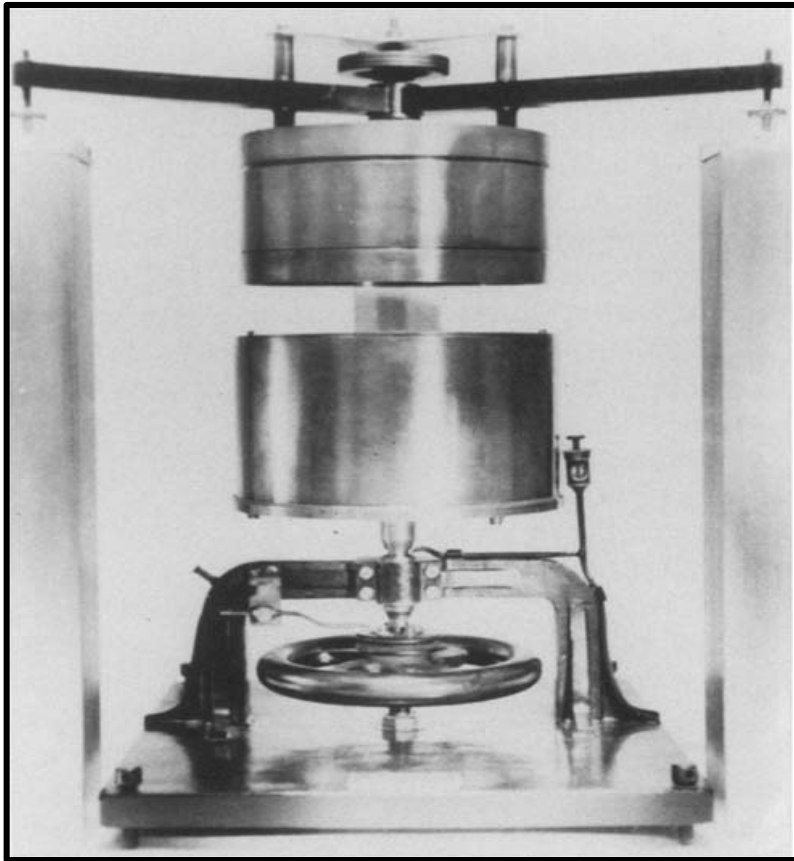
Historical Background

- The study of flow behavior of fluid comprised between two cylinder has a rich experimental history.
- Sir George Gabriel Stokes first mentioned it in the *Transactions of the Cambridge Philosophical Society* in 1848.
- Max Margules was the first to propose constructing a viscometer based on the rotating cylinder principle in 1881.
- In 1888, Arnulph Mallock did an experiment on the viscosity of water using a pair of concentric cylinders.
- In 1890, Couette published a study of viscosity using a pair of cylinders where the outer one was rotating and inner one suspended on a fiber.

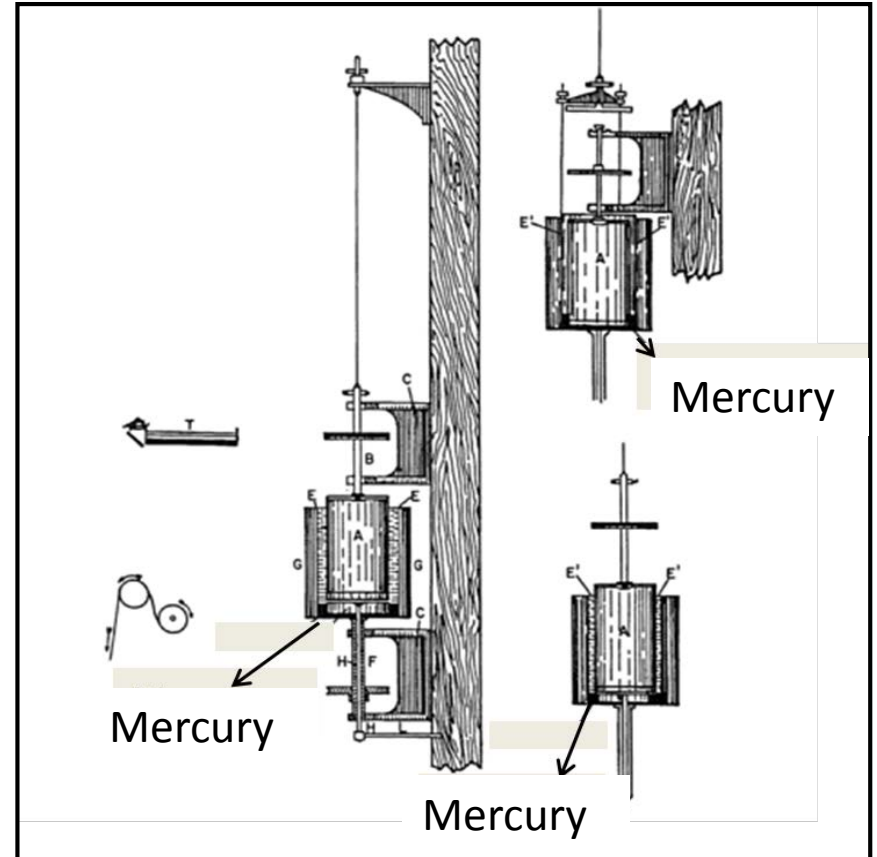


Maurice Couette (1858 – 1953)
Rheologica Acta 33:357-368 (1994)

Early Viscometer Designs



The cylinder viscometer of M. Couette (1888)
(Rheologica Acta 33:357-368 (1994))



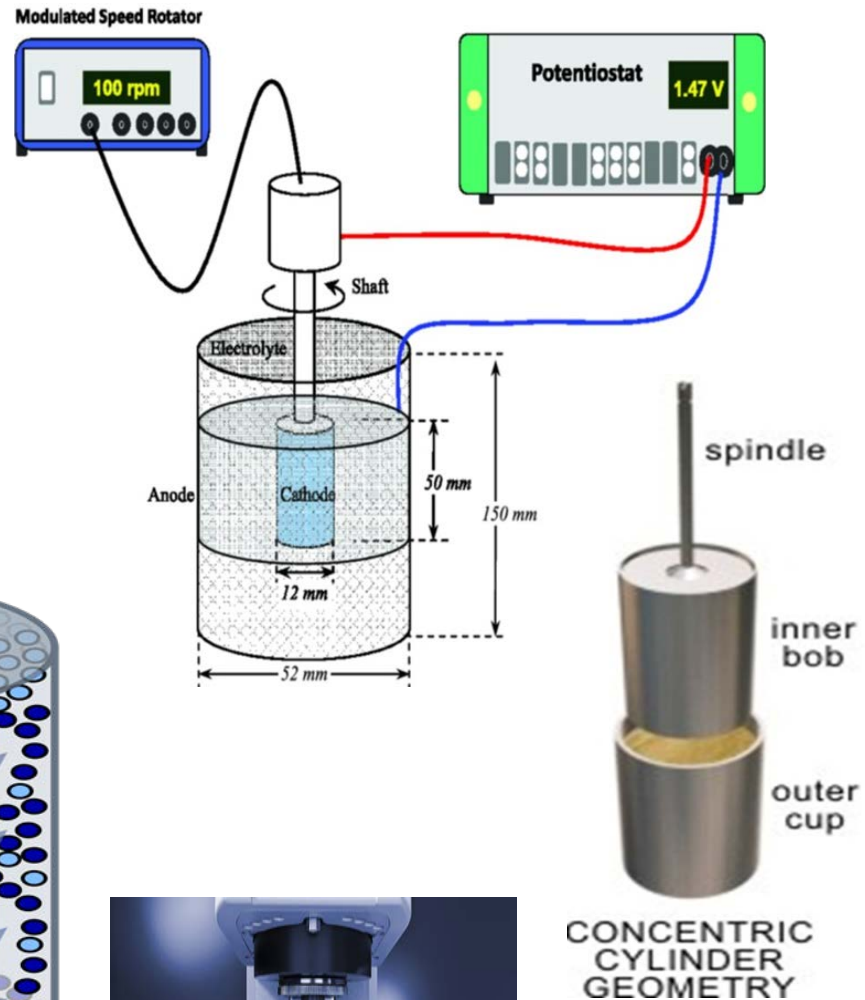
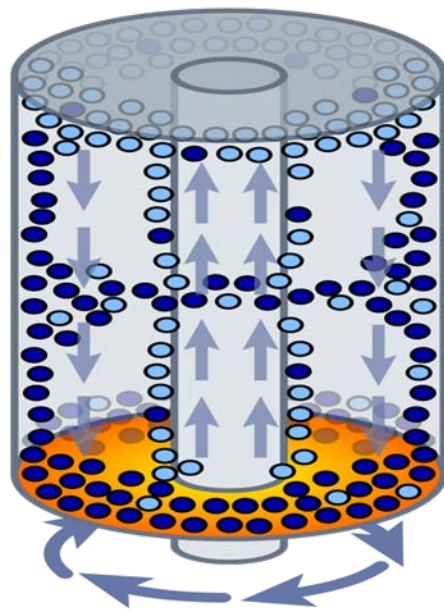
Arnulph Mallock's apparatus (1888)*

From 18th century to now, many developments in this field have occurred and are still ongoing .

***Reference:** C. David Andereck and F. Hayot, "Ordered and Turbulent Patterns in Taylor-Couette Flow", The Ohio State University, Columbus, Ohio, NATO ASI Series, Series B: Physics Vol.297

Industrial Applications of Annular Flows

- Production of oil and gas
- Centrifugally-driven separation processes
- Electrochemical cells
- Viscometers
- Tribology
- Hydraulic equipment
- Chemical reactors



Navier-Stokes Equations in Polar Coordinates

Polar Component Form

r – component

$$\begin{aligned} & \rho \left(\frac{\partial v_r}{\partial t} + v_r \left(\frac{\partial v_r}{\partial r} \right) + \frac{v_\theta}{r} \left(\frac{\partial v_r}{\partial \theta} \right) + v_z \left(\frac{\partial v_r}{\partial z} \right) - \frac{v_\theta^2}{r} \right) \\ &= - \left(\frac{\partial p(r, z)}{\partial r} \right) + \rho g_r + \mu \left(\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (r v_r)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} + \frac{\partial^2 v_r}{\partial z^2} - \frac{2}{r^2} \left(\frac{\partial v_\theta}{\partial \theta} \right) \right) \end{aligned}$$

θ – component

$$\begin{aligned} & \rho \left(\frac{\partial v_\theta}{\partial t} + v_r \left(\frac{\partial v_\theta}{\partial r} \right) + \frac{v_\theta}{r} \left(\frac{\partial v_\theta}{\partial \theta} \right) + v_z \left(\frac{\partial v_\theta}{\partial z} \right) + \frac{v_r v_\theta}{r} \right) \\ &= - \frac{1}{r} \left(\frac{\partial p(r, z)}{\partial \theta} \right) + \rho g_\theta + \mu \left(\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (r v_\theta)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{\partial^2 v_\theta}{\partial z^2} + \frac{2}{r^2} \left(\frac{\partial v_r}{\partial \theta} \right) \right) \end{aligned}$$

z – component

$$\begin{aligned} & \rho \left(\frac{\partial v_z}{\partial t} + v_r \left(\frac{\partial v_z}{\partial r} \right) + \frac{v_\theta}{r} \left(\frac{\partial v_z}{\partial \theta} \right) + v_z \left(\frac{\partial v_z}{\partial z} \right) \right) \\ &= - \left(\frac{\partial p(r, z)}{\partial z} \right) + \rho g_z + \mu \left(\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right) \end{aligned}$$

Navier-Stokes Equations for 1- D Model

- **r – component**

$$-\frac{\rho v_{\theta}^2}{r} = -\left(\frac{\partial p}{\partial r}\right)$$

- **θ – component**

$$0 = -\left(\frac{d}{dr}\left(\frac{1}{r}\frac{d}{dr}(rv_{\theta})\right)\right)$$

- **z - component**

$$0 = -\frac{\partial p}{\partial z} - \rho g_z$$

- **Outer Cylinder is Rotating**

- $T_z = (-\tau_{r\theta}) \Big|_{r=\kappa R} (2\pi\kappa RL)(\kappa R)$
 $= 4\pi\mu\Omega_0 R^2 L \left(\frac{\kappa^2}{1-\kappa^2}\right)$

- **Inner Cylinder is Rotating**

- $T_z = (-\tau_{r\theta}) \Big|_{r=R} (2\pi RL)(R)$
 $= 4\pi\mu\Omega_i R^2 L \left(\frac{\kappa^2}{1-\kappa^2}\right)$

- **Outer Cylinder is Rotating and Inner Cylinder is Stationary**

B.C. 1 at $r = \kappa R$, $v_{\theta} = 0$

B.C. 2 at $r = R$, $v_{\theta} = \Omega_0 R$

$$v_{\theta}(r) = \Omega_0 R \left(\frac{\left(\frac{r}{\kappa R} - \frac{\kappa R}{r}\right)}{\left(\frac{1}{\kappa} - \kappa\right)}\right)$$

- **Inner Cylinder is Rotating and Outer Cylinder is Stationary**

B.C. 1 at $r = \kappa R$, $v_{\theta} = \Omega_i R$

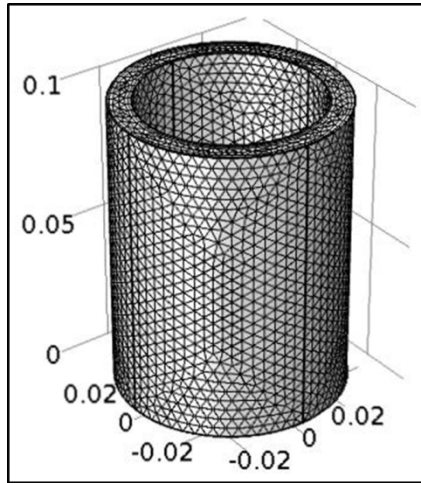
B.C. 2 at $r = R$, $v_{\theta} = 0$

$$v_{\theta}(r) = \Omega_i \kappa R \left(\frac{\left(\frac{R}{r} - \frac{r}{R}\right)}{\left(\frac{1}{\kappa} - \kappa\right)}\right)$$

← **Torque Equation**

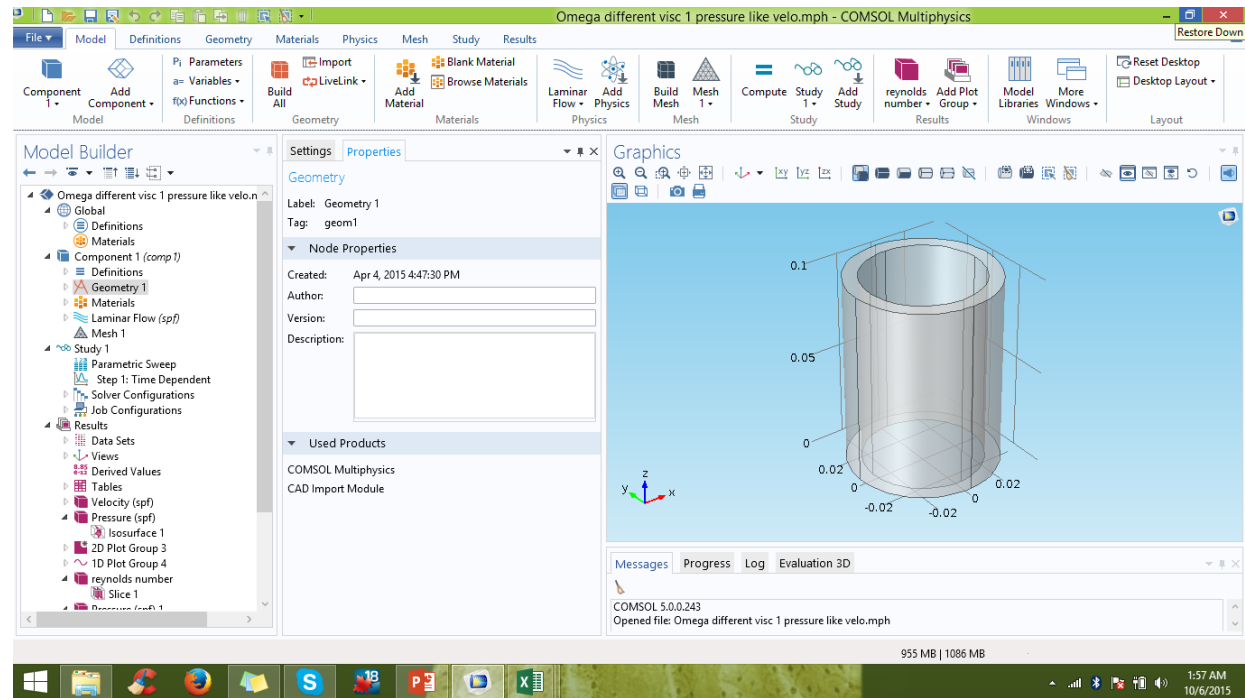
Computing on CFD Module in COMSOL

Meshed Geometry



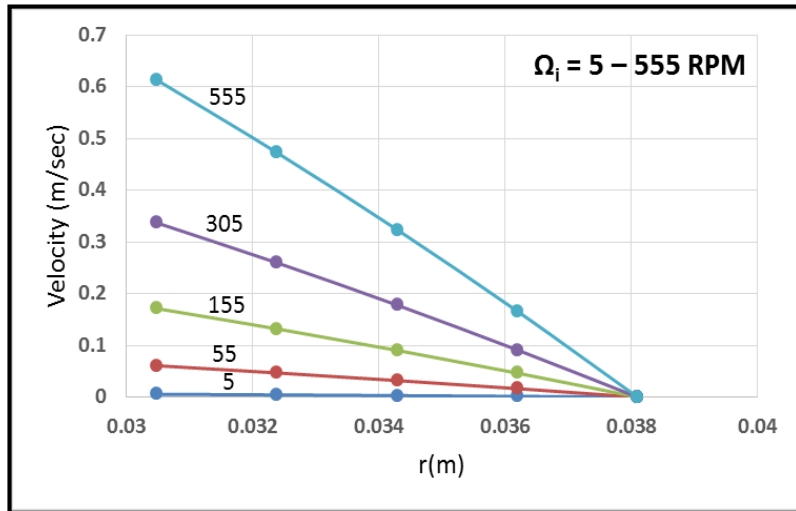
The 3-D geometry of concentric rotating cylinder system where the inner cylinder is rotating and outer cylinder is stationary was developed by using the *COMSOL Computational Fluid Dynamics (CFD)* module for determination of the velocity and pressure profiles.

3D meshing element type
Nodes: Cylinder
Boolean & Partitions

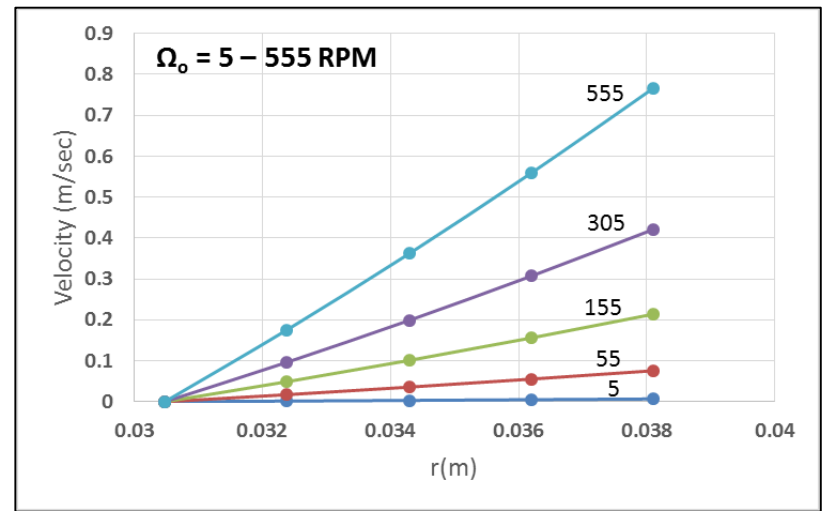


1-D Model

Velocity Profiles in the Annulus at Various Rotational Speeds

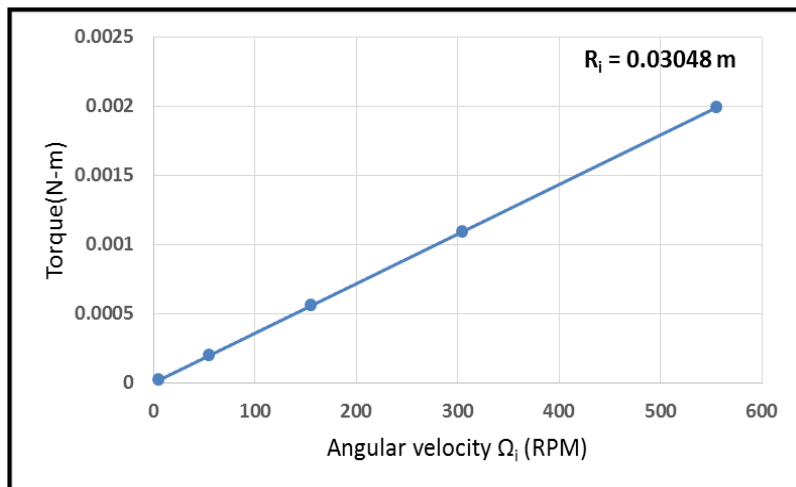


When inner cylinder is rotating

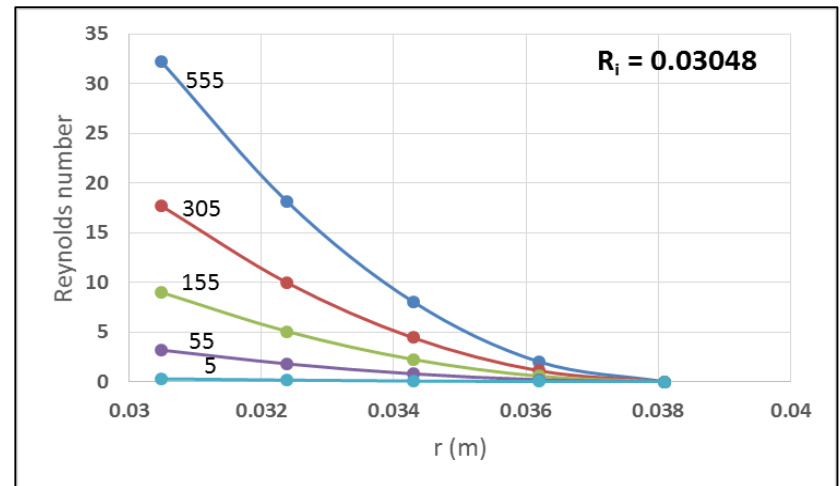


When outer cylinder is rotating

Torque Profile at Various Rotational Speeds

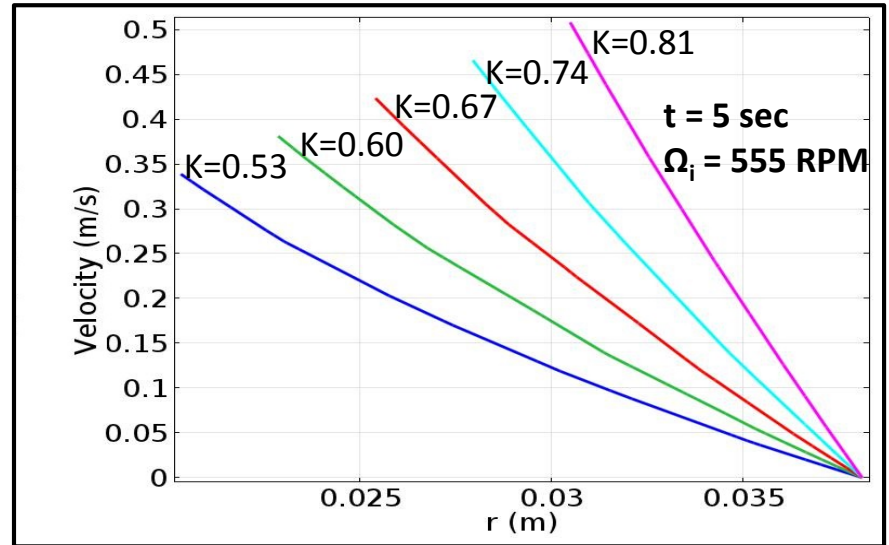
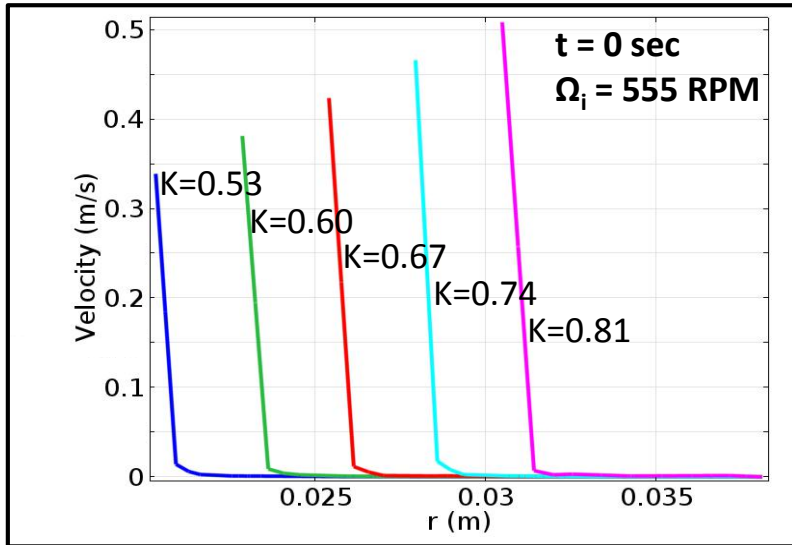


Reynolds Number Distribution Profile

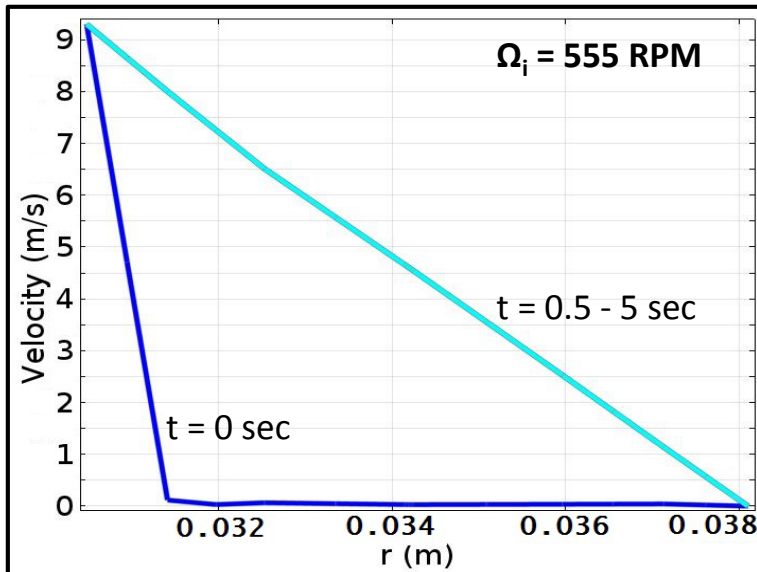


3 - D Model Images from COMSOL

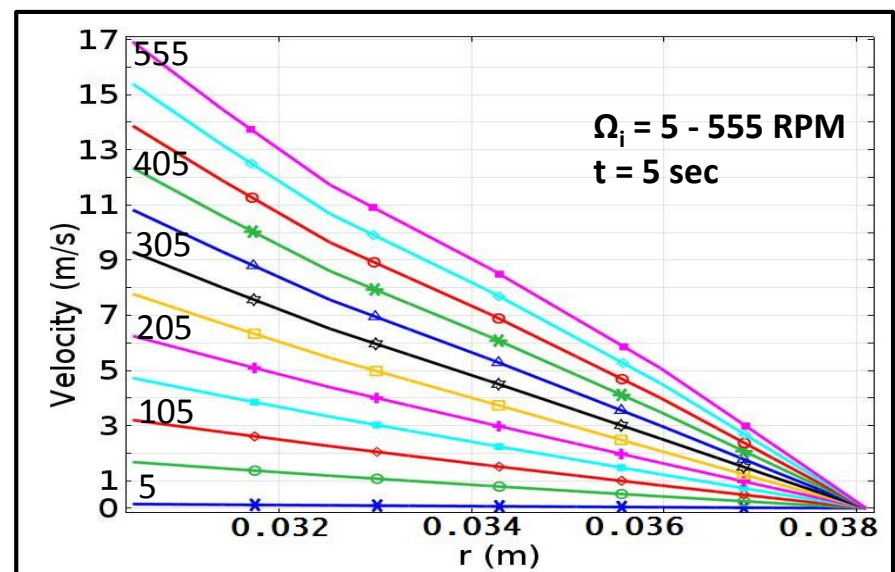
Effect of Cylinder Inner Radius on Fluid Velocity Profiles



Developing Velocity Profiles During Cylinder Startup

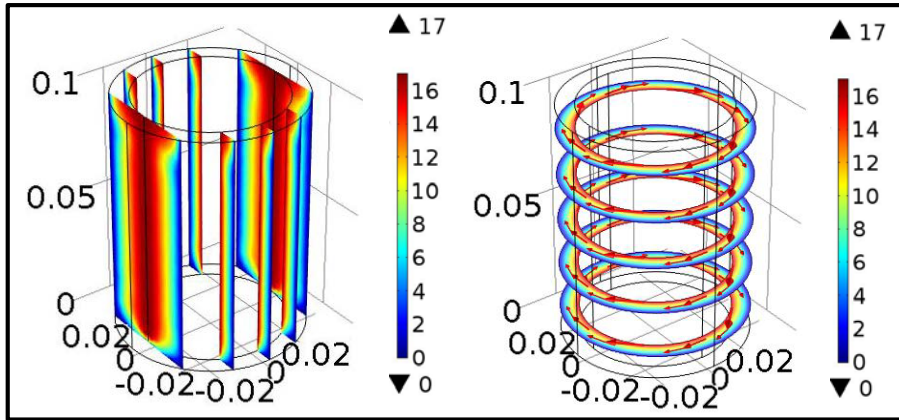


Velocity Profiles in the Annulus at Various Rotational Speeds

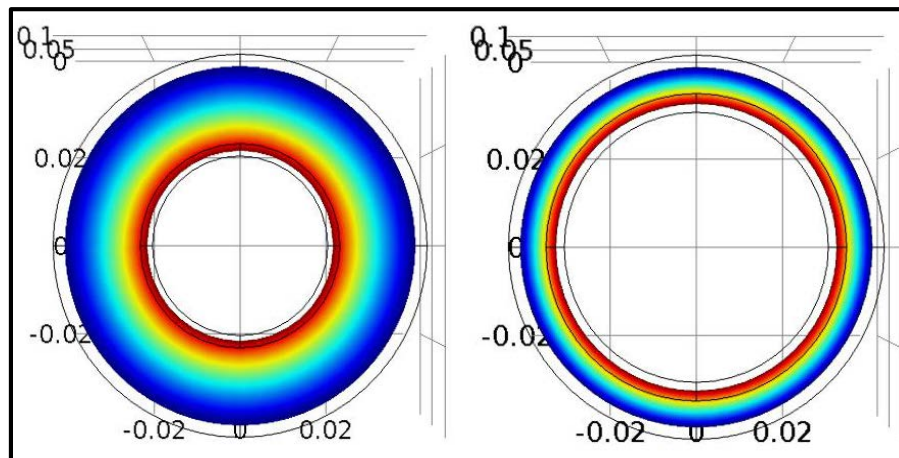


Velocity Profiles for 3-D Model

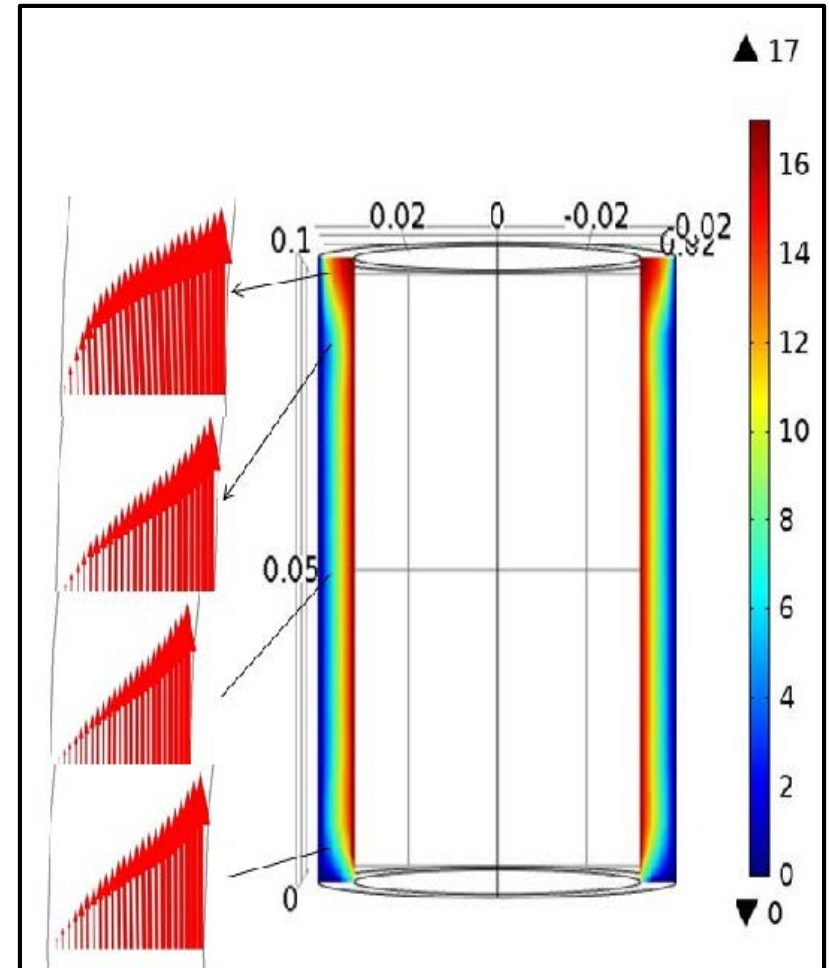
Rotating Inner Cylinder and Stationary Outer Cylinder



Velocity profiles at $t = 5$ sec and $\Omega_i = 555$ RPM



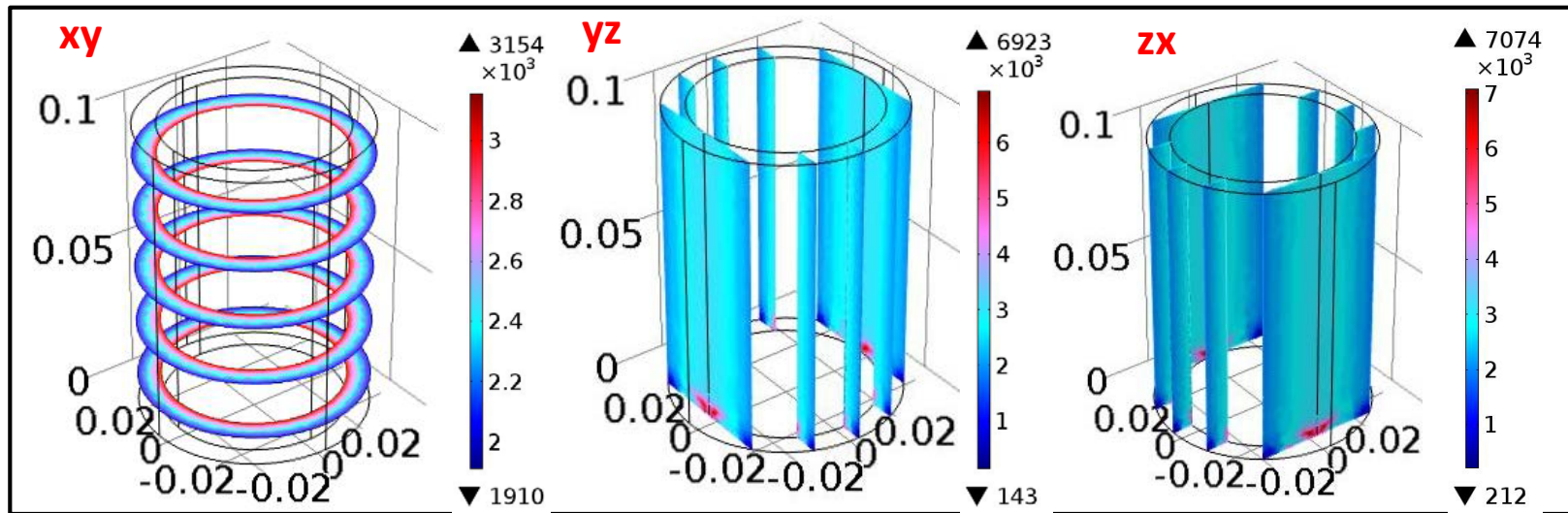
Velocity profiles when R_i is varied



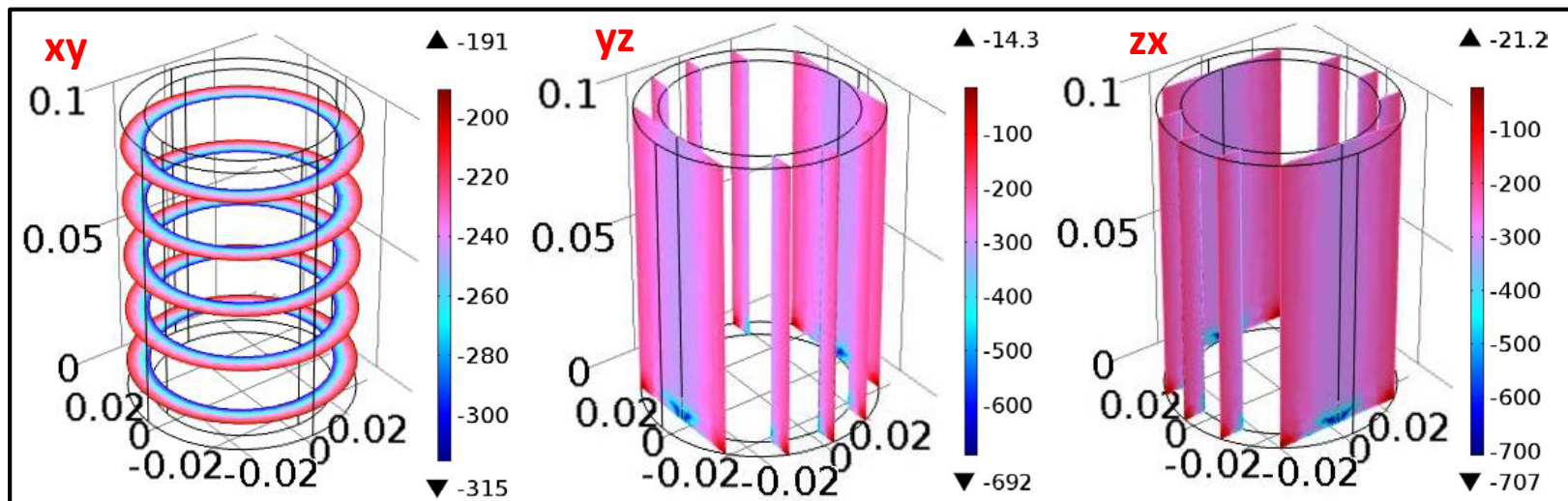
Velocity profile along the length of the cylinder

Profiles for 3-D Model in Different planes

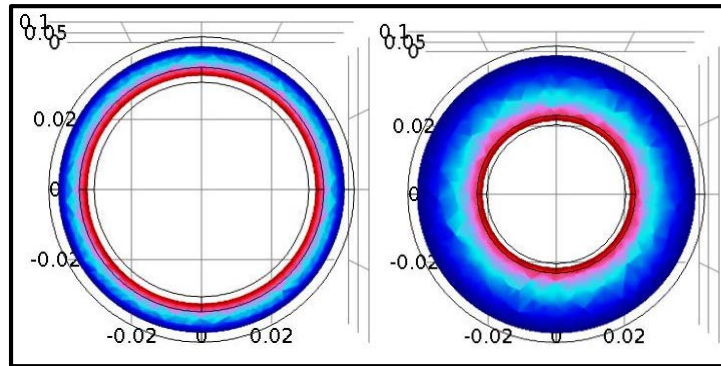
Shear rate profiles at $t = 5$ sec and $\Omega_i = 555$ RPM



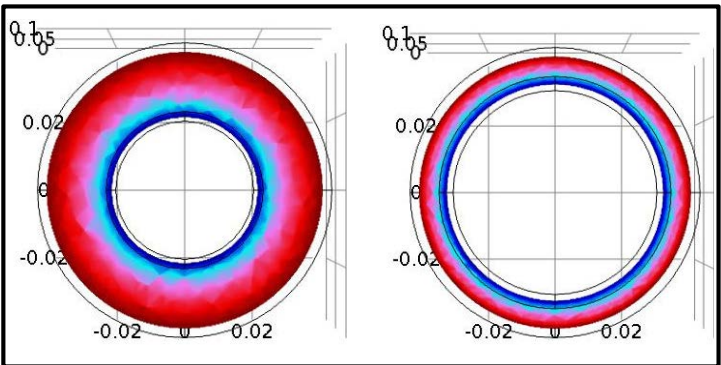
Shear stress profiles at $t = 5$ sec and $\Omega_i = 555$ RPM



Profiles for 3-D Model in Different planes

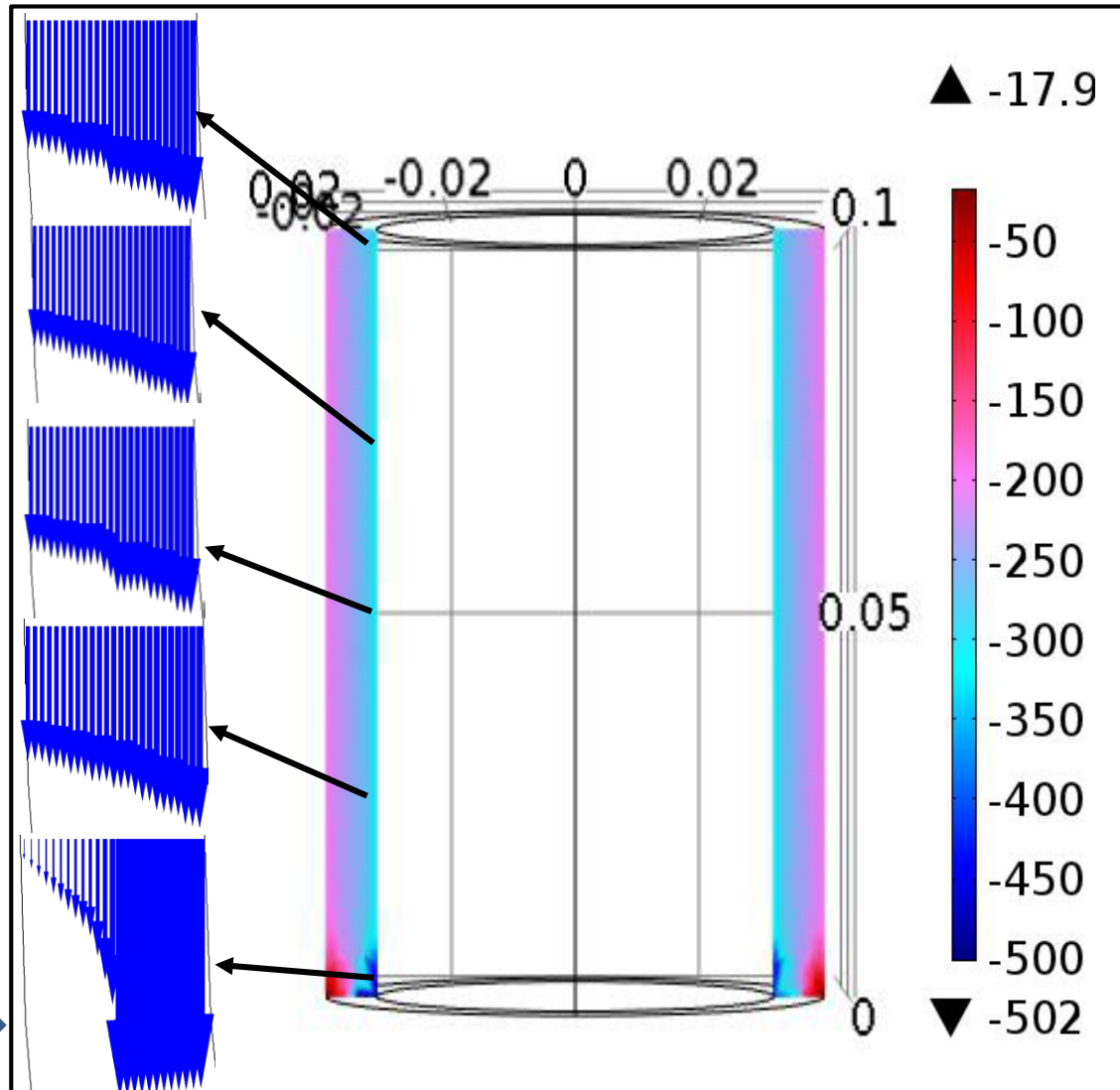


Shear rate profiles when R_i is varied



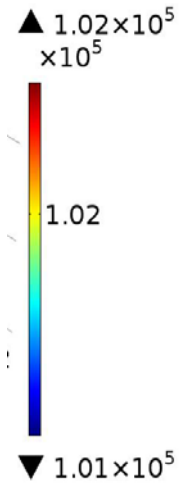
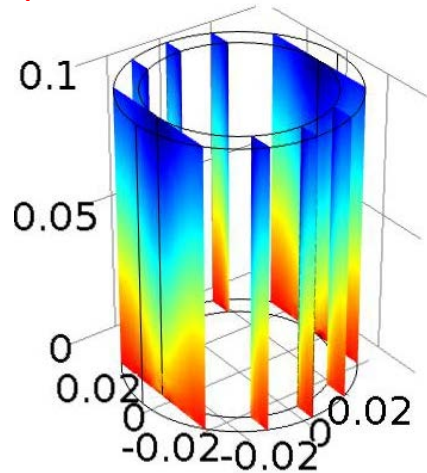
Shear stress profiles when R_i is varied

Shear stress profile versus length of the cylinder

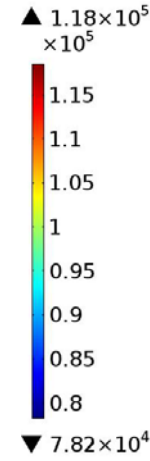
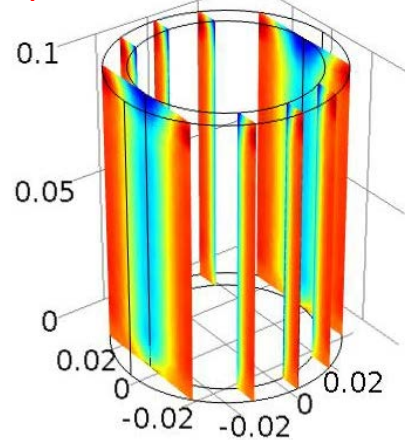


Pressure Profiles for 3-D and 1-D Model

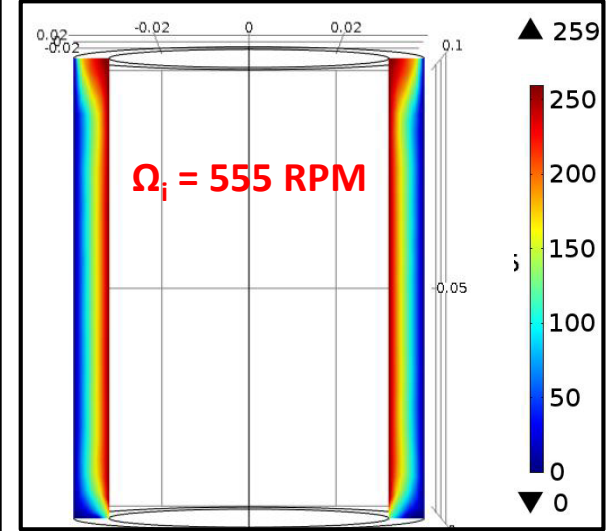
$\Omega_i = 55 \text{ RPM}$



$\Omega_i = 555 \text{ RPM}$

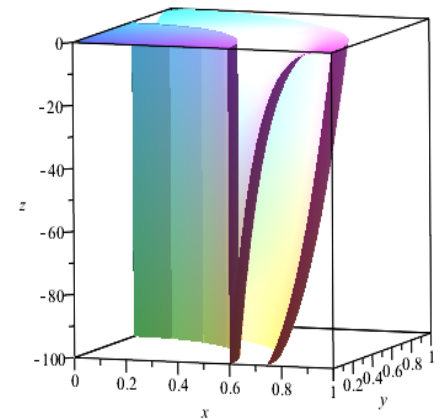
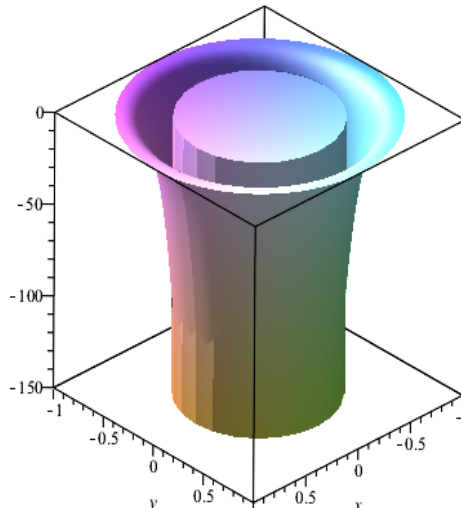
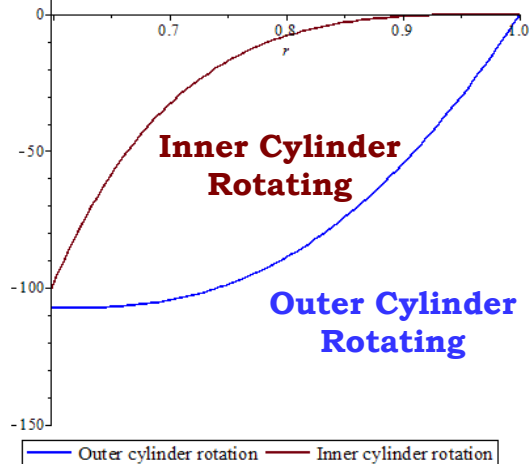


3-D Pressure profiles at t= 5 sec



Reynolds number distribution

$P(r,z)$

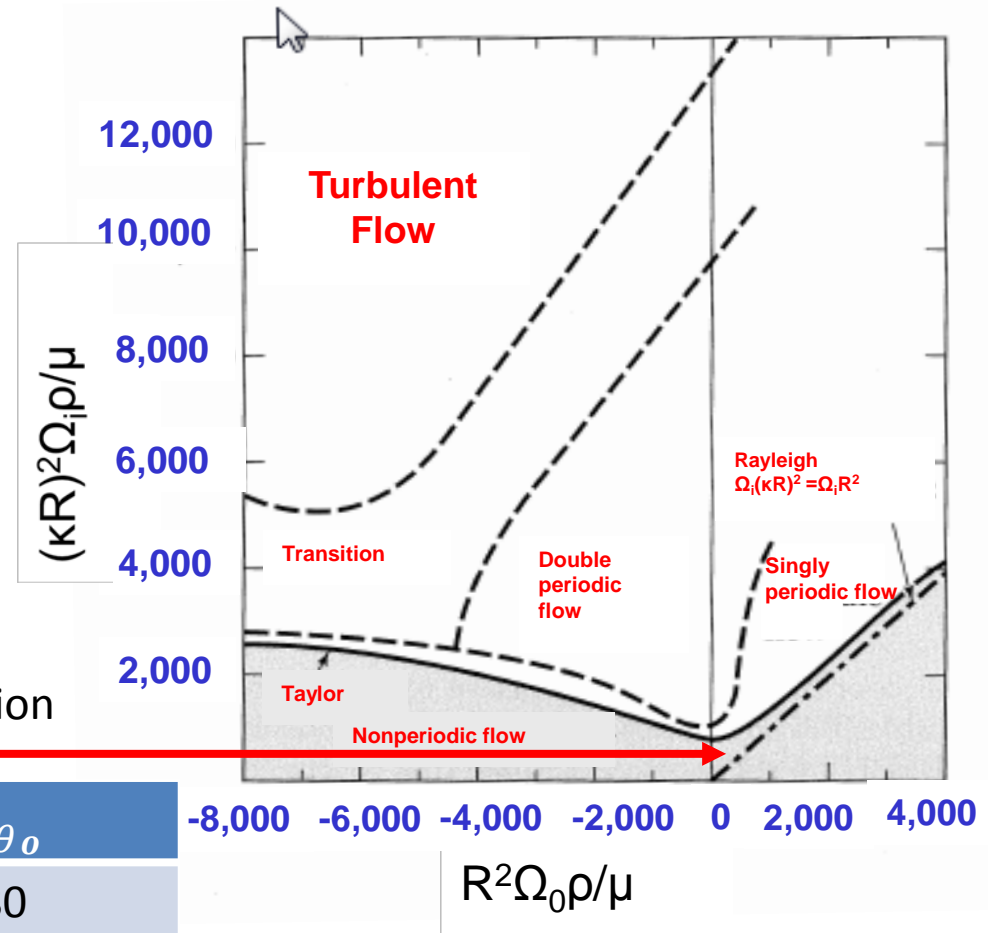


1-D Pressure profiles at t= 5 sec 555 RPM

Computational Challenges

When we try to run the system for turbulent flow, it became difficult to converge the model and if it converge for lower values of rotational speeds, we were unable to get stable results.

We lie in this region



Omega	v_{θ_i}	v_{θ_o}
55	51	80
555	516	806

v_{θ_i} = When Inner Cylinder is rotating and Outer Cylinder is Stationary

v_{θ_o} = When Outer Cylinder is rotating and Inner Cylinder is Stationary

Key Observations

- The velocity profile approaches a becomes fully developed state only after traveling a distance that is several times the annular gap width.
- The analytical solution for the case where the fluid velocity profile depends only on the azimuthal component of the velocity vector in the radial direction is compared to the 3-D solution and shown to have good agreement in the fully-developed zone.
- The pressure gradient increases with increasing rotational speed.
- The value of shear stress acting on inner rotating cylinder is minimum and it is at it's maximum on the outer stationary wall.
- By this study a foundation has been laid for further application to non-Newtonian fluids used in drilling muds or separation.