

# COMSOL-based Nuclear Reactor Kinetics Studies at the High Flux Isotope Reactor

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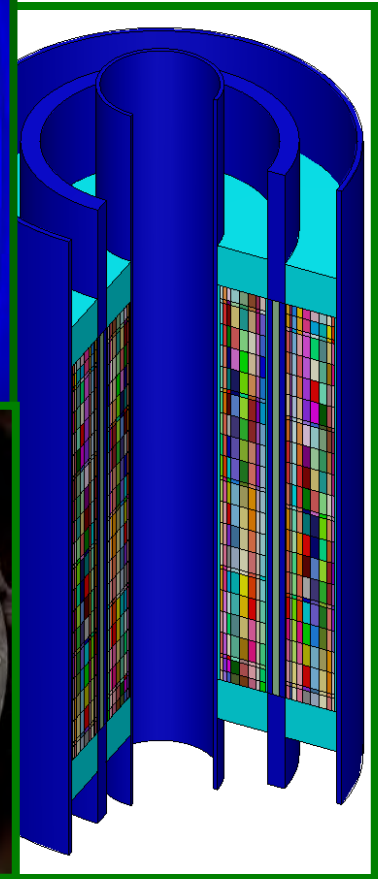
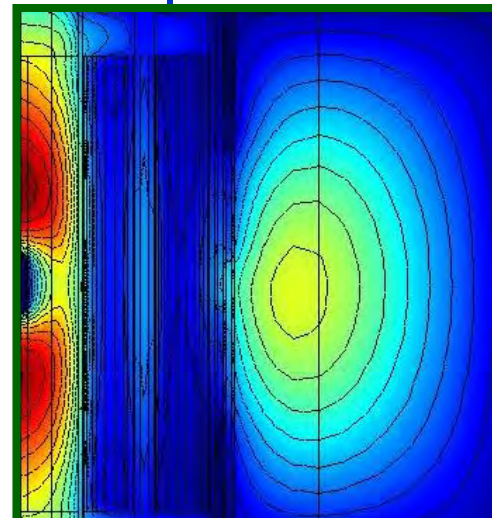
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Presented at the



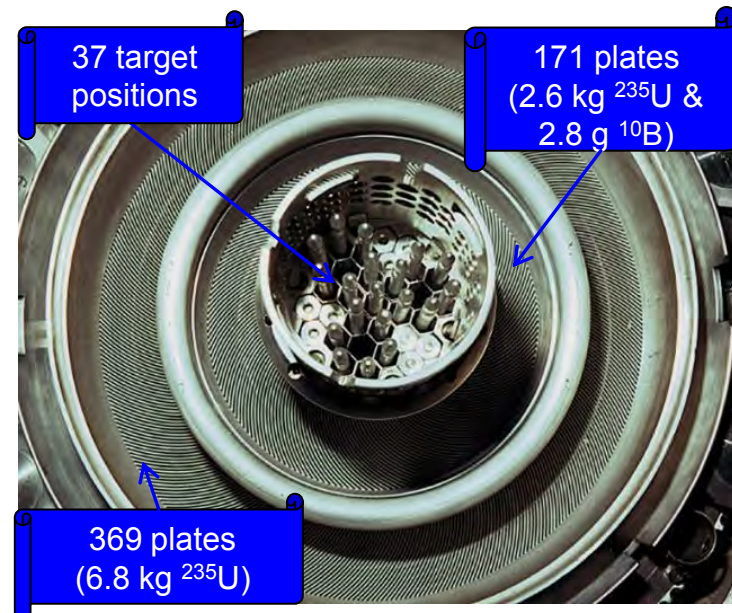
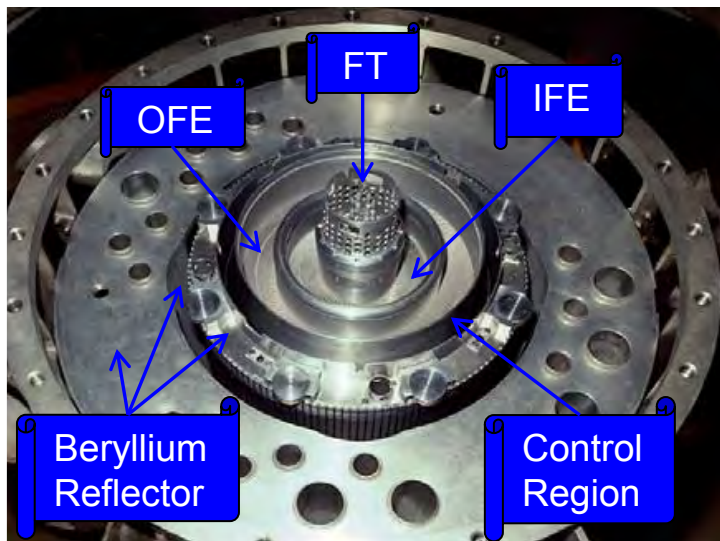
# Presentation Outline



- **Brief HFIR background**
- **Brief review of reactor physics concepts**
- **Reactor Kinetics Studies**
  - Nuclear data generation via NEWT
  - Control cylinder ejection transient
  - Space-time kinetics equation-based modeling methodology
- **Results**
- **Conclusions**

# Beryllium reflected, light-water cooled, pressurized, flux-trap type reactor.

- Currently operates at 85 MW<sub>th</sub>
- Cycle length 21 – 26 calendar days
- Two Fuel Elements [Inner Fuel Element (IFE) and Outer Fuel Element (OFE)]
- Highly Enriched Uranium fuel (~93 wt.% <sup>235</sup>U) in the form of U<sub>3</sub>O<sub>8</sub>-Al with Al-6061 clad
- Two Control Elements (CEs) for regulation and safety purposes
- Cold and thermal neutron scattering, isotope production, materials irradiation, Neutron Activation Analysis

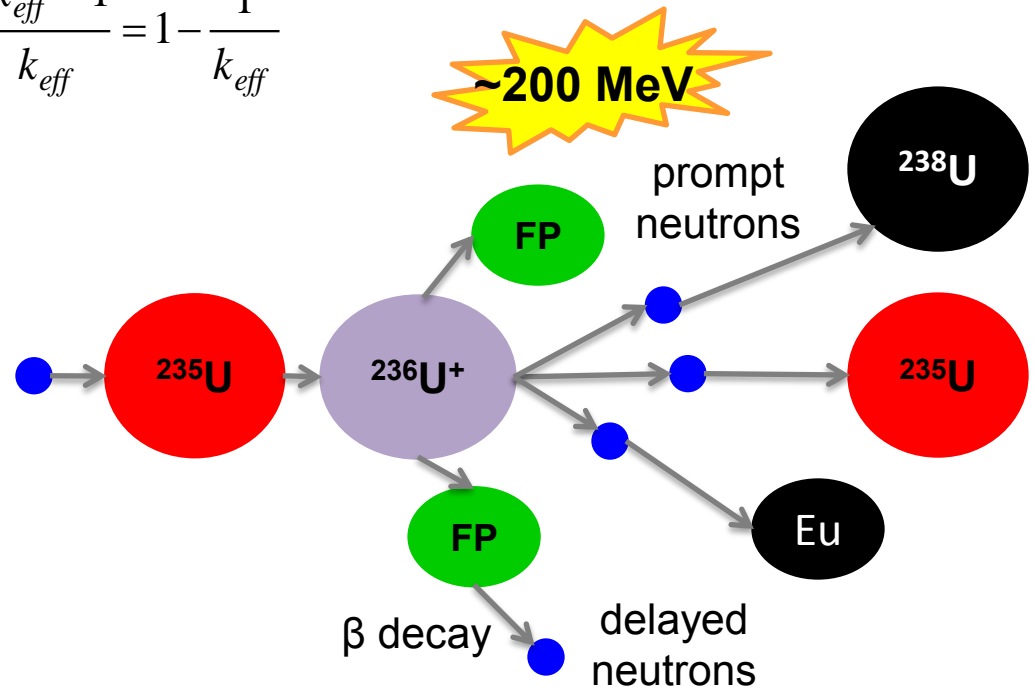
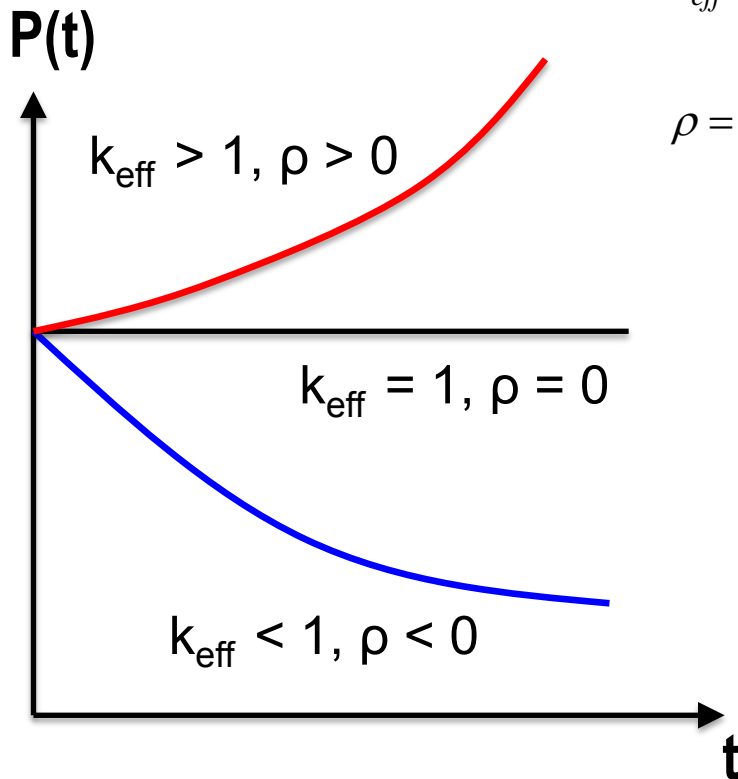


# If positive reactivity is inserted, the power will increase. If negative reactivity is inserted, the power will decrease.

- The effective neutron multiplication factor ( $k_{eff}$ ) is the ratio of the number of neutrons produced in generation "i+1" to the number produced in generation "i"
- Reactivity ( $\rho$  cents, dollars,  $\Delta k/k$ , etc.) is a measure of the deviation from critical

$$k_{eff} = \frac{\text{\# of neutrons in generation "i+1"}}{\text{\# of neutrons in generation "i"}} = \frac{\text{production}}{\text{absorption + leakage}}$$

$$\rho = \frac{k_{eff} - 1}{k_{eff}} = 1 - \frac{1}{k_{eff}}$$



# PDE coefficient form application mode.

## Multi-Energy-Group Neutron Diffusion

$$\frac{1}{v^g} \frac{\partial \phi^g}{\partial t} - \nabla \cdot (D^g \nabla \phi^g) + \left( \Sigma_a^g + \sum_{g'=1, \neq g}^G \Sigma_s^{g \rightarrow g'} \right) \phi^g =$$

$$(1 - \beta_{eff}) \chi_p^g \sum_{g'=1}^G \nu \Sigma_f^{g'} \phi^{g'} + \sum_{g'=1, \neq g}^G \Sigma_s^{g' \rightarrow g} \phi^{g'} + \sum_{i=1}^I \lambda_i \chi_i^g C_i$$

$g = 1:3$   
 $i = 1:6$

- $\phi^g$  neutron flux (neutrons/m<sup>2</sup>-s)
- $v^g$  average neutron velocity (m/s)
- $D^g$  diffusion coefficient (m)
- $\Sigma_a^g$  absorption cross section (1/m)
- $\Sigma_s^{g \rightarrow g'}$  scattering cross section g→g' (1/m)
- $\chi_p^g$  probability of prompt neutron born in g
- $\nu$  average # of neutrons emitted per fission
- $\Sigma_f^{g'}$  fission cross section (1/m)

## Delayed Neutron Precursor Concentration

$$\frac{\partial C_i}{\partial t} + \lambda_i C_i = \beta_i \sum_{g=1}^G \nu \Sigma_f^g \phi^g$$

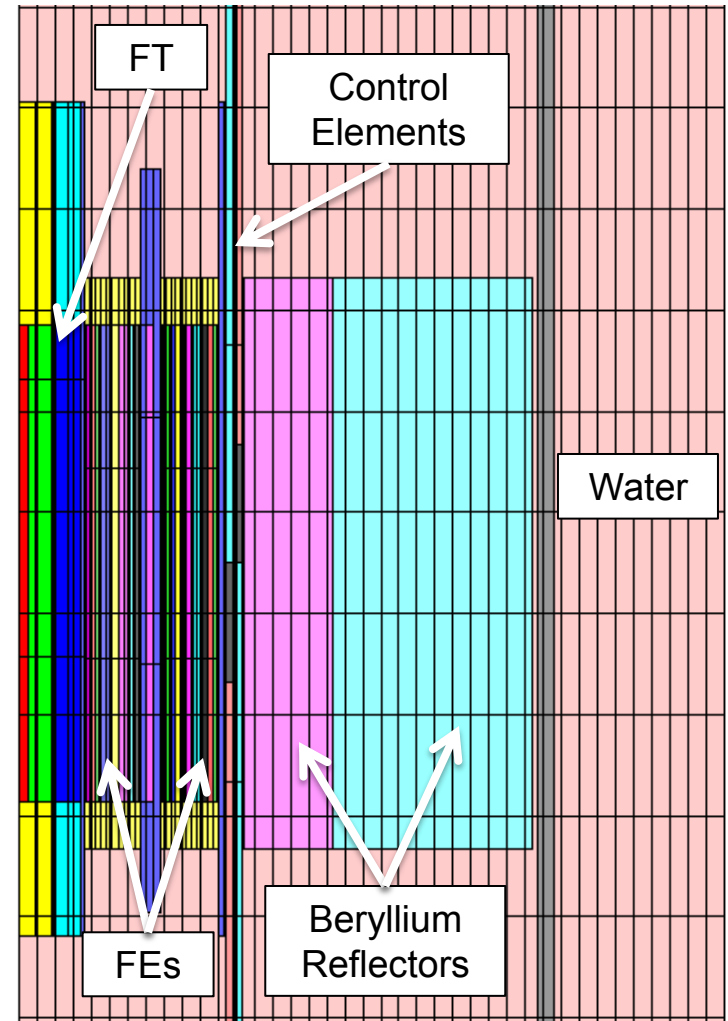
- $C_i$  DNP concentration (neutrons/m<sup>3</sup>)
- $\lambda_i$  Decay constant (1/s)
- $\chi_i^g$  probability of delayed neutron born in g
- $\beta_i$  fraction of neutrons born delayed

$$\beta_{eff} = \sum_{i=1}^6 \beta_i$$

# The TRITON/NEWT sequence in SCALE is used to calculate nuclear data.

- 2-D neutron discrete-ordinates code
- Provides a solution for multigroup transport calculations
- Calculates the spatial flux distribution and prepares collapsed cross sections

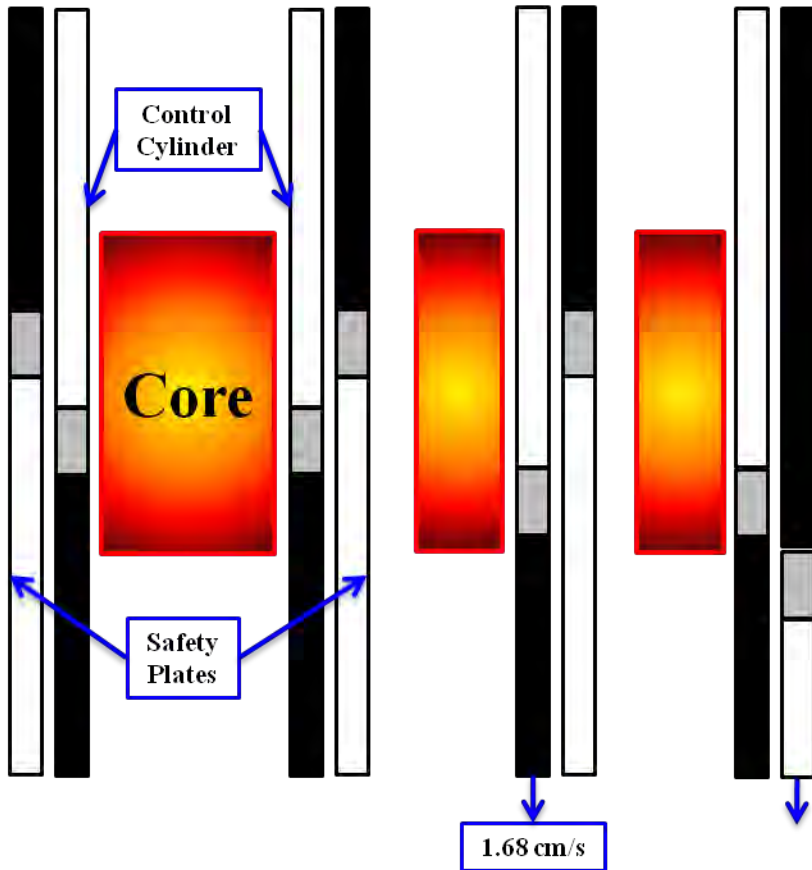
3-group #	238-group #	Lower Energy
1	44	100 keV
2	199	0.625 eV
3	238	10 $\mu$ eV



NEWT input modified from the model documented in:

Dr. G. Ilas, et. al., New Cross Section Processing Methodology for HFIR Core Analysis, PHYSOR-2008, Interlaken, Switzerland, Sep. 2008.

If the control cylinder is ejected, positive reactivity would be inserted; thus, giving rise to a power transient.



- Transient initiated by a control cylinder ejection
  - $v_{cc} = -1.68 \text{ cm/s}$  (-0.662 in/s)
- Initial reactor power = 1 kW
  - Zero power condition (lowest critical power and worst case scenario)
- Power scram set point = 5.001 MW
- Safety plate response time = 10 ms

$$\frac{d^2 \Delta z_{sp}(t)}{dt^2} = -[4g - 19.7g\Delta z_{oce}] \frac{m}{s^2}, \text{ for } a \geq g$$

otherwise,

$$\frac{d^2 \Delta z_{sp}(t)}{dt^2} = -g \left( \frac{m}{s^2} \right)$$

# Three study steps are solved in sequential order.

## 1. Eigenvalue study

- Good spatially-dependent solution, but normalized to maximum value
- Solution used as the initial values (starting guesses) for study step 2

## 2. Stationary study

- Set up constraint (ODE) to normalize fluxes and determine  $k_{eff}$

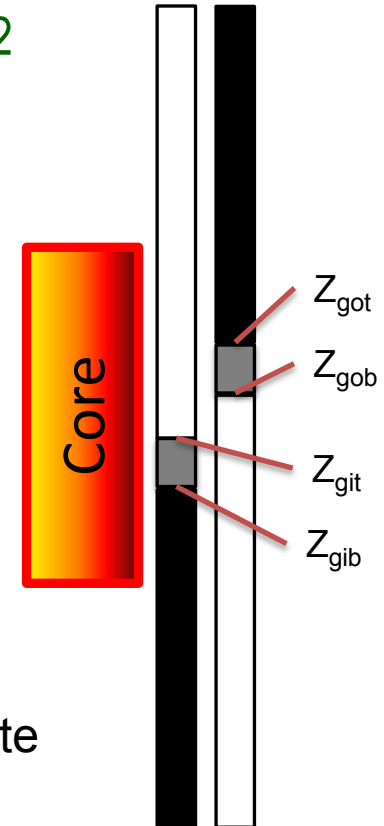
$$k_{eff} : \left( \iiint_V \sum_{g=1}^3 \kappa \Sigma_f^g \phi^g dV \right) - P_o = 0 \quad (\kappa \approx 3.1 \times 10^{-11} \text{ J/fission})$$

- Solution used as initial values for study step 3

## 3. Time-dependent study

- Define moving interfaces, i.e.  $Z_{gib}(t) = -2.54[\text{cm}] - 1.68[\text{cm/s}] * t[\text{s}]$
- Assign axially-dependent properties (cross sections) to simulate control element movement, i.e.  $\text{if}(z < Z_{gib}, \Sigma_{bi}, \text{if}(z < Z_{git}, \Sigma_{gi}, \Sigma_{wi}))$
- Smoothing functions applied to transitions from high absorption to low absorption, i.e.  $\text{flc2hs}(z - z_2, \text{scale})$
- Track power as a function of time

$$P(W) = \iiint_V \sum_{g=1}^3 (k^g \Sigma_f^g \phi^g) dV$$

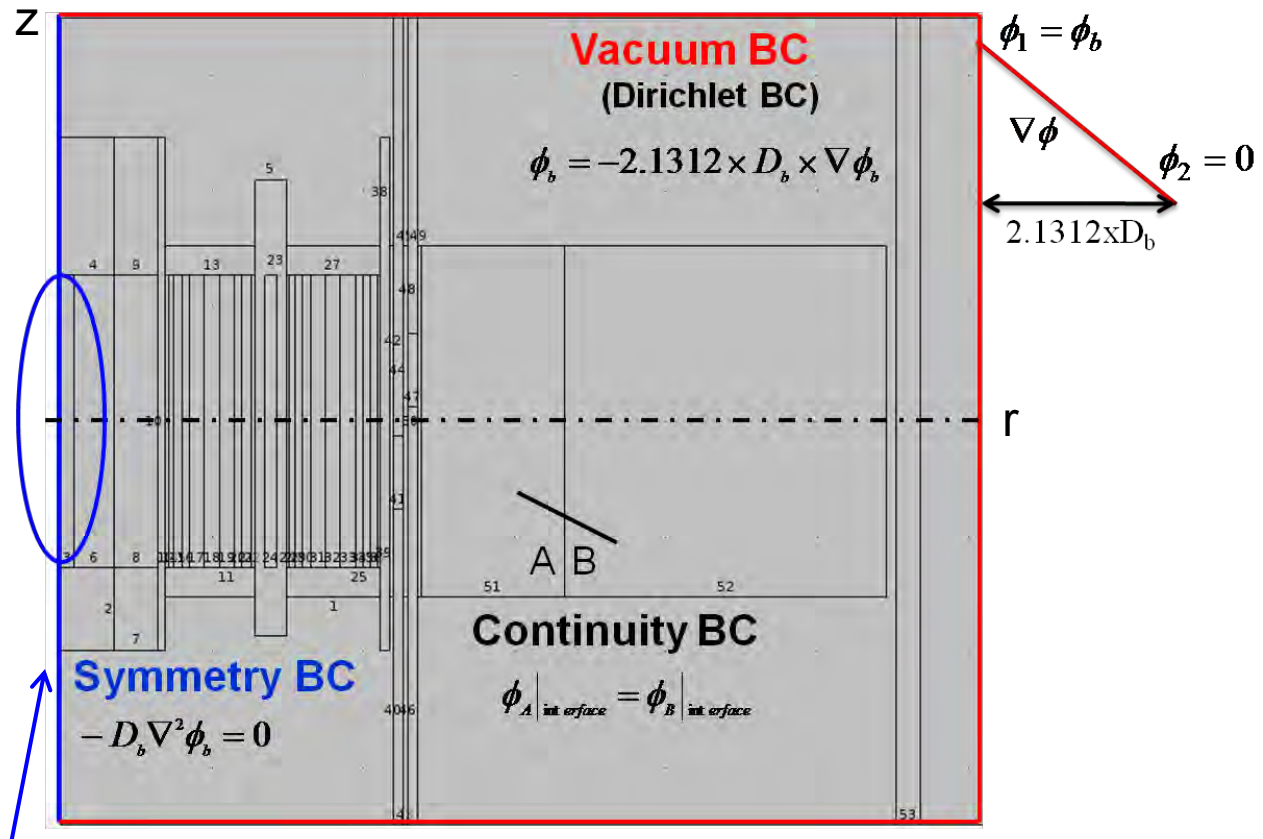




# 2-D axisymmetric geometry and vacuum boundary conditions are utilized.

$$\left. \begin{aligned} \mathbf{n} \cdot (c \nabla u + \alpha u - \gamma) + qu &= g - h^T \mu \\ hu &= r \end{aligned} \right\} \text{on boundary (d}\Omega\text{)}$$

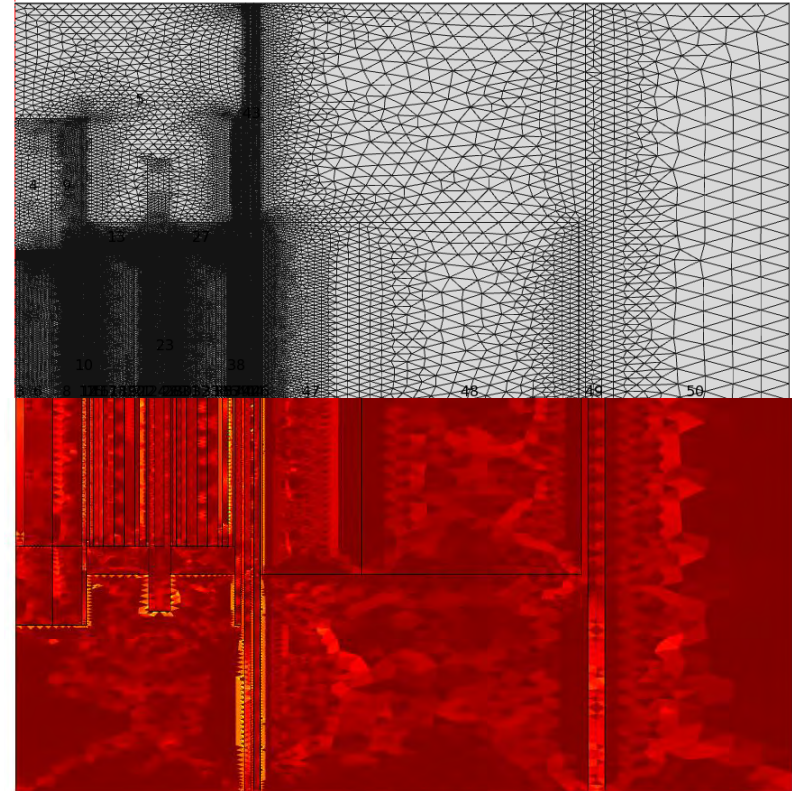
- Symmetry BC defined at the axial centerline
- Vacuum BCs defined at the 3 outer pool boundaries
- Continuity BCs defined for all interior boundary interfaces



core axial centerline.

# COMSOL's built-in mesh generator used to discretize the geometry and Direct solvers are utilized.

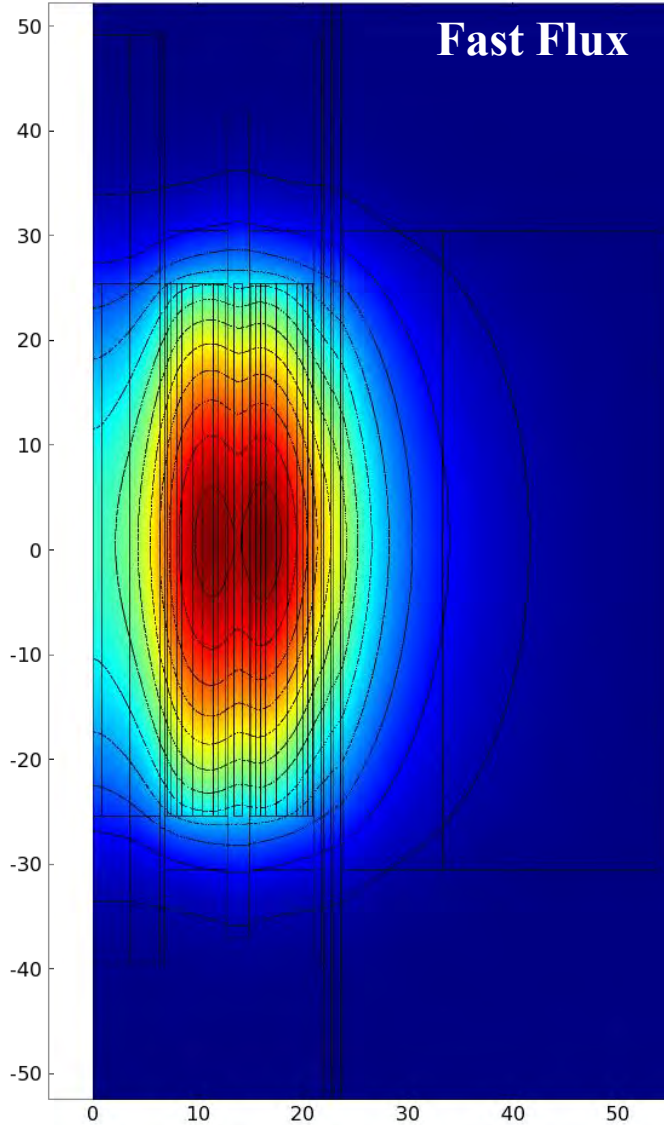
- Mapped mesh in moving domains
- Boundary layers in narrow domains located near steep flux gradients
- Free triangular mesh elsewhere
  - “Extremely fine” in core region (+refinements)
  - “Extra fine” in pool water outside of Be reflector
- Each model set up with ~100-150k elements
  - ~1-2 million DOF → 24 hr solution time
  - 3 compute nodes, dual quad core processors, 64 GB RAM
- PARDISO for stationary and eigenvalue
  - Efficient, but does not run in distributed parallel mode
- MUMPS for transient calculations
  - Less efficient, but runs in distributed parallel mode



# Beginning-of-cycle neutron fluxes.

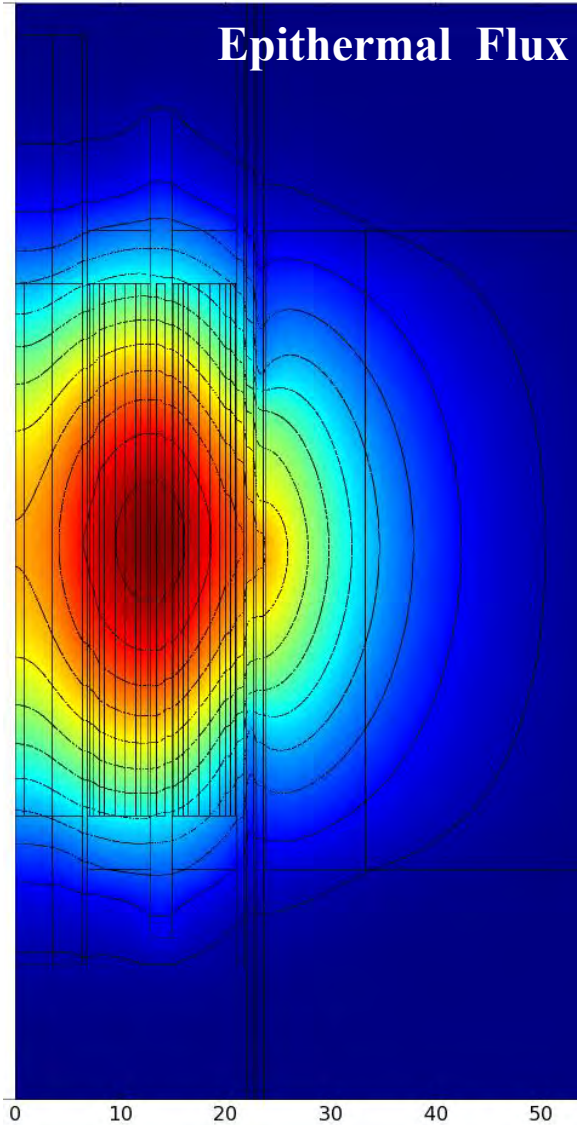
$(0.1 \text{ MeV} \leq E_n \leq 20 \text{ MeV})$

**Fast Flux**



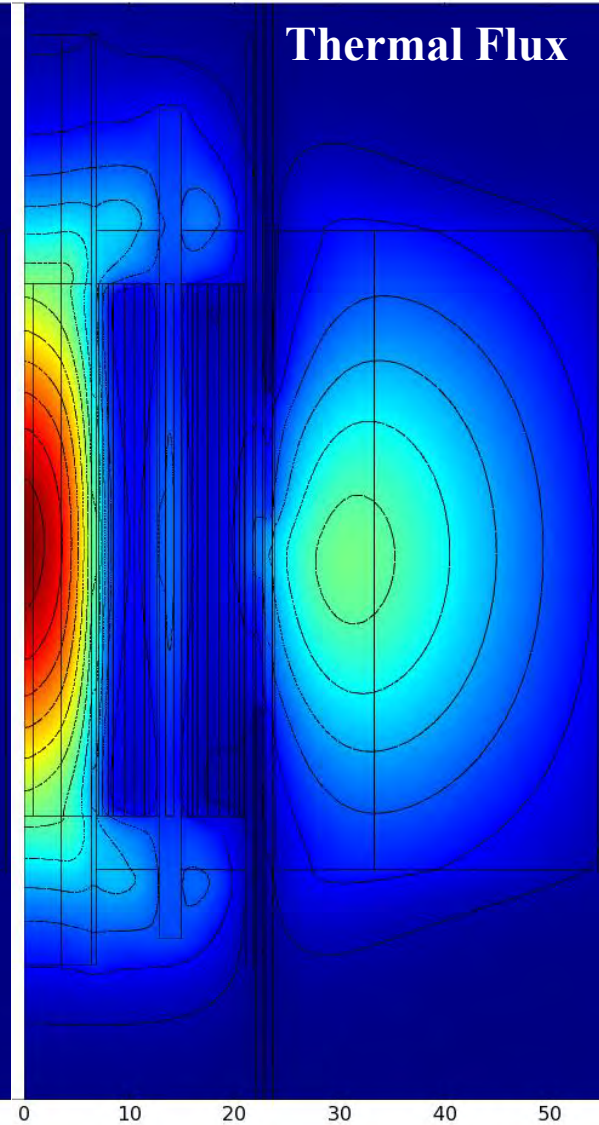
$(0.625 \text{ eV} \leq E_n \leq 0.1 \text{ MeV})$

**Epithermal Flux**

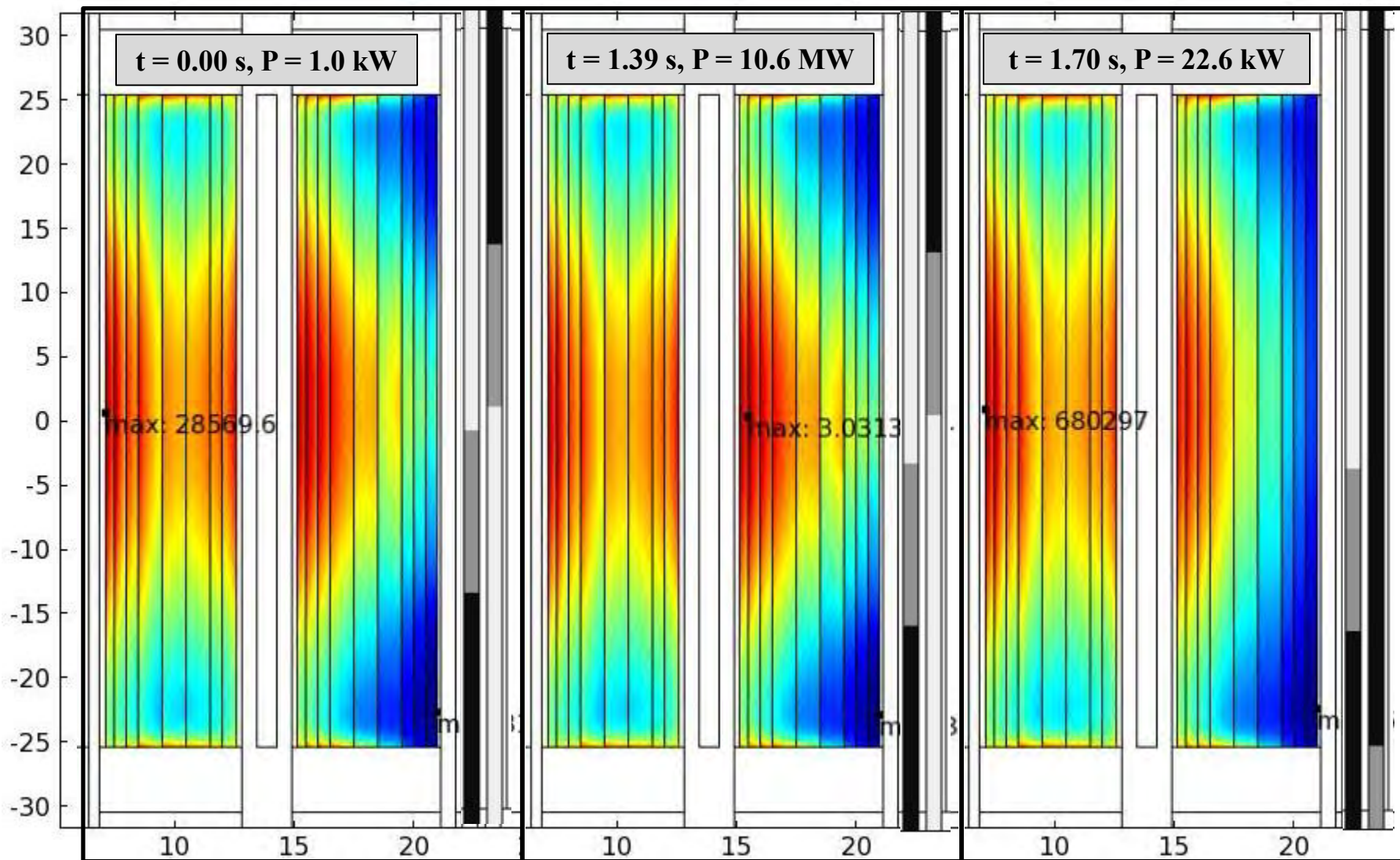


$(1 \times 10^{-5} \text{ eV} \leq E_n \leq 0.625 \text{ eV})$

**Thermal Flux**



# Power shifts to the OFE during control cylinder ejection and then back to IFE during safety plate insertion.



# Summary and Conclusions

- **COMSOL-based neutron diffusion models of HFIR were created via equation-based modeling**
  - 3 neutron energy groups and 6 delayed neutron precursor groups
  - 2-D axisymmetric geometry
  - Nuclear data derived from TRITON/NEWT sequence in SCALE
- **New space-time (PDE and ODE modes) and point kinetics (ODE mode) methodologies were developed in COMSOL**
  - Point kinetics are much more computationally efficient and were shown to produce accurate results for small perturbations
- **Additional results and methods documented in full length paper**
- **COMSOL is also being used at the HFIR for thermal hydraulic and structural analyses**