



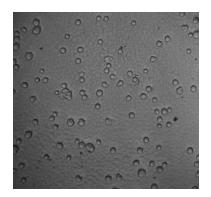
Simulation of Pearl-Chain Formation in Acoustics

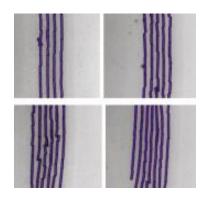
Baasch Thierry, Ivo Leibacher and Jürg Dual Institute for Mechanical Systems, ETHZ

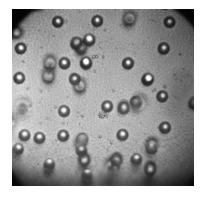




Motivation









Provide physical insights with Simulation and Experiments

References: 1) Nyborg, Wesley L. "Theoretical criterion for acoustic aggregation." *Ultrasound in medicine & biology* 15.2 (1989): 93-99. 2) Collino, Rachel R., et al. "Acoustic field controlled patterning and assembly of anisotropic particles." *Extreme Mechanics Letters* 5 (2015): 37-46.

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Physical Modelling

Mechanical contact forces

- Smoothed potentials (stiff/non-linear springs etc.)
- Non-smooth potentials

Primary & secondary acoustic radiation forces

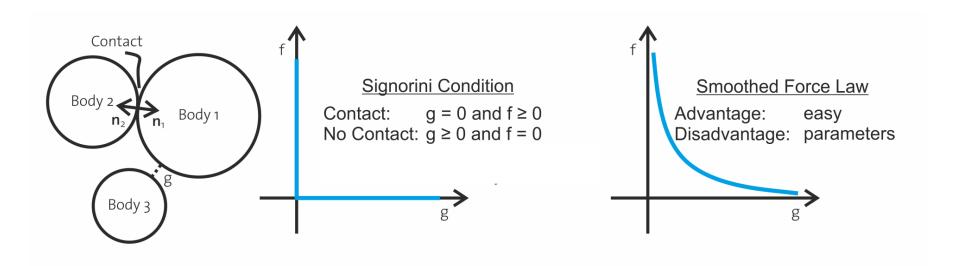
- Semi analytically
- COMSOL

First order Stokes drag

No hydrodynamic interactions are considered



Contact Forces, in the Context of Non-smooth Dynamics

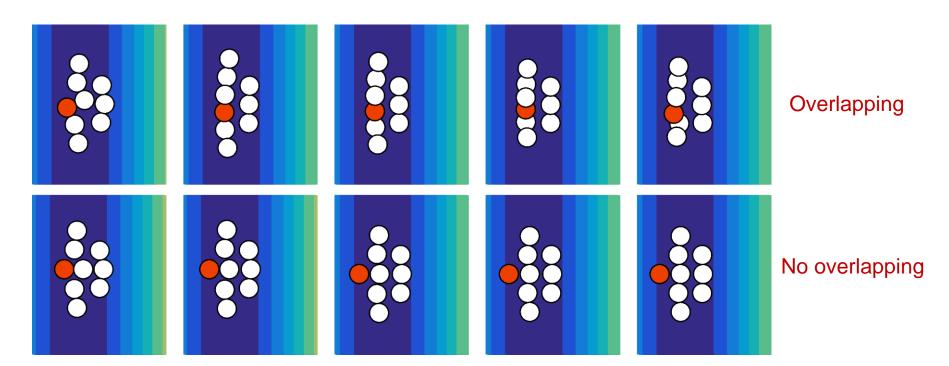


¹⁾ Moreau, Jean J. "Unilateral contact and dry friction in finite freedom dynamics." Nonsmooth mechanics and Applications. Springer Vienna, 1988. 1-82



Correction to Numerical Drift

- Standard algorithm is velocity based: Steady drift can occur
- Solved By Drift Correction algorithm!



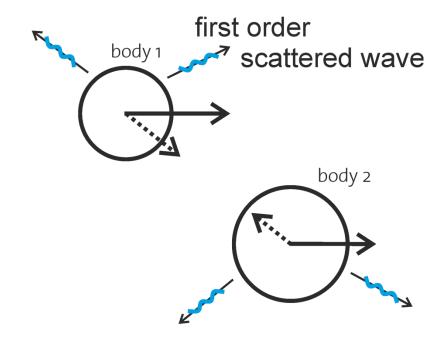
References: 1) Nützi, Gabriel Elias. Non-Smooth Granular Rigid Body Dynamics with Applications to Chute Flows. Diss. ETH Zurich, 2016.



Acoustic Radiation Forces (ARF)

acoustic background wave

primary and secondary acoustic radiation force



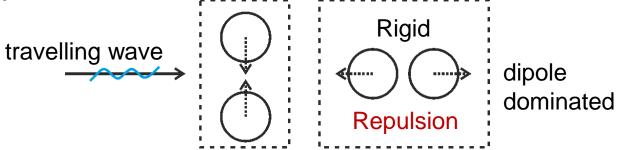
References: 1) Silva, Glauber T., and Henrik Bruus. "Acoustic interaction forces between small particles in an ideal fluid." Physical Review E 90.6 (2014): 063007.

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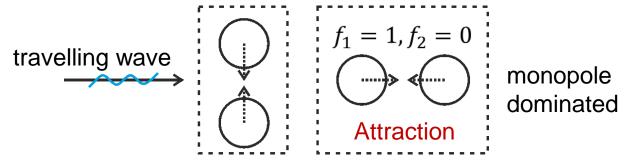


Direction of Secondary ARF

Example 1



Example 2 (classical Bjerknes, kr≪1)



References: 1) Silva, Glauber T., and Henrik Bruus. "Acoustic interaction forces between small particles in an ideal fluid." Physical Review E 90.6 (2014): 063007.

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Some considerations in 1D Standing Wave

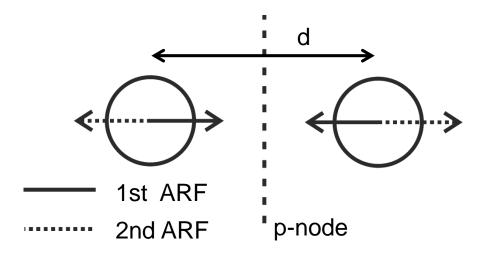
Primary acoustic radiation force

$$F_{rad} = 4\pi\Phi(f_1, f_2)ka^3E_{ac}\sin(2k_y y)$$

Secondary ARF close to p-node

$$F_{int} \approx \frac{8\pi}{3d^4} a^6 E_{ac} (1 - \bar{\rho})^2 \cos^2(k_y y) (1 - 3\cos(\phi))$$
, for small d

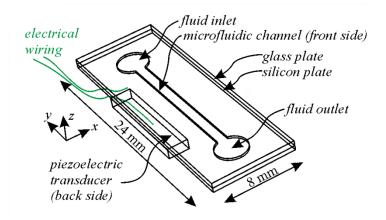
Equilibrium
$$\frac{F_{rad}}{F_{int}} = 1 \Rightarrow \bar{d} \propto \left(\frac{1}{a^2 k^2} \cdot \frac{\Phi(f_1, f_2)}{(1 - \bar{\rho})^2}\right), \bar{d} = \frac{d}{a}$$





Experimental Setup

- Bulk acoustic wave device
- Piezo transducer excites resonances
- Channel is etched into silicon wafer.
- Glass slide bonded on top

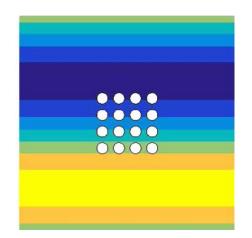




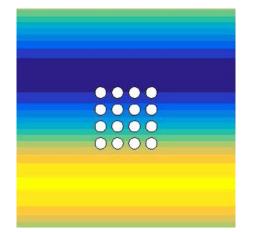
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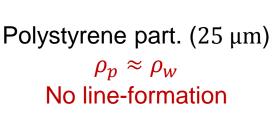
Simulations



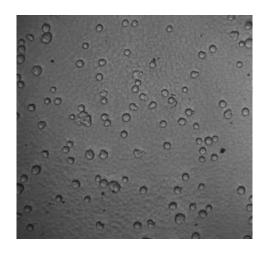
Glass part. (10 μ m) $\rho_p > \rho_w$ Line-formation!

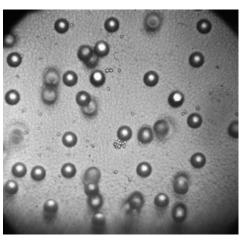


immersed in water frequency = 1.5 MHz



Experiments







Rotation of Particle Clumps

- Amplitude modulation of 2 orthogonal waves
- Simulated with copolymer particles (f_1 =0.768, f_1 =0.034)
- Particle diameter 100μm
- Inspired by the work of Thomas Schwarz

Rotation of particle clumps with amplitude modulation of two ultrasonic modes

Copolymer particles (Ø 17 µm)

Average rotational speed: 44 rpm

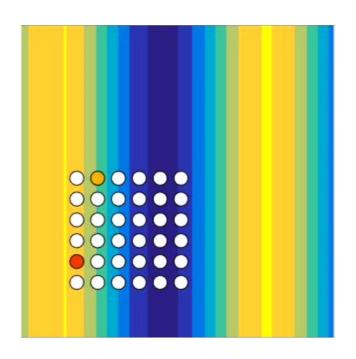
Frequency: 1689 kHz

Chamber size: 3 mm × 3 mm

Schwarz, Petit-Pierre, Dual, JASA 133(3), 2013

ETH

Eidgenössische Technische Hochschule Zürich Swiss Federal Institute of Technology Zurich



¹⁾ Schwarz, Thomas. *Rotation of particles by ultrasonic manipulation*. Diss. Diss., Eidgenössische Technische Hochschule ETH Zürich, Nr. 21572, 2013, 2013.

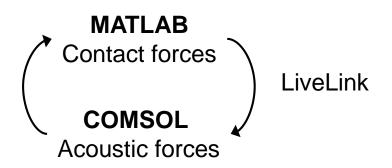


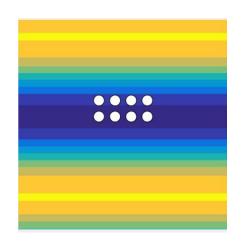
Comsol

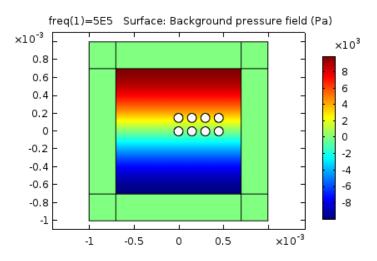
- Simulating complete scattering
- No assumptions regarding: wavelength, scattering coefficients, rescattering events etc.
- Simulations may take more time

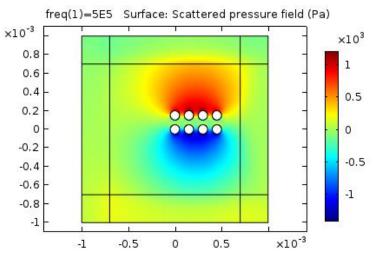


Outlook: Using Comsol (2-D Proof of Principle)











Outlook

- Include hydrodynamic effects
- Simulate more particles
- Simulate more complex geometries
- Include acoustic streaming