



## A Black-Oil Model for Primary and Secondary Oil-Recovery in Stratified Petroleum Reservoirs



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## Objective

Development of the black-oil model in COMSOL Multiphysics platform.

- Implementation of a numerically stable formulation.
- Oil-recovery scenarios:
  - Pressure depletion with solution-gas drive mechanism
  - Waterflooding
  - Gas injection



## The Physical Problem

### Recovery of financially significant



# Primary oil-recovery (Pressure depletion):

- Natural reservoir energy
- Solution-gas drive mechanism : Expansion of oil & evolved

#### solution gas Secondary oil-recovery:

- Pressure maintenance
- Injection fluids: water,

#### gas

- Oil displacement Enhanced oil-recovery (EOR):
- Thermal processes, miscible fluids, surfactants



## The "Black-Oil Model" Approach

Prediction of oil production dynamics & reservoir conditions.





### The "Black-Oil Model" System



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 $\rho_o = \frac{\rho_{\rm Os} + R_{so}\rho_{\rm Gs}}{B_o}$ 

Saturation

Formation volume

Solution gas-oil ratio

Intrinsic permeability

Relative permeability

Velocity

factor

Viscosity

Density

 $\rho_g = \frac{\rho_{\rm Gs}}{B_a}$ 

 $\rho_{\rm W} = \frac{\rho_{\rm Ws}}{R_{\rm W}}$ 



## Numerical Challenge

Finite Element Method:

Non-linearity & coupling weakened

More stable formulation using terms rearrangement!



### Phase Formulation (Chen, 2000)

Pressure variable :  $p = p_o$  Total velocity :  $u = \sum u_\beta$ , for  $[\overline{\beta} = \overline{g}, \overline{o}, w]$ 

**1 Pressure equation :**   $\nabla \cdot \boldsymbol{u} = \sum B_{\alpha} \left( a_{\alpha} - \varphi S_{\alpha} \frac{\partial}{\partial t} \left( \frac{1}{d_{\alpha}} \right) - \boldsymbol{u}_{\alpha} \cdot \nabla \left( \frac{1}{d_{\alpha}} \right) \right) - B_{\alpha} \left( R_{co} a_{\alpha} + \frac{\varphi S_{o}}{d_{\alpha}} \frac{\partial R_{so}}{\partial t} + \frac{1}{d_{\alpha}} \cdot \nabla R_{so} \right)$  **General Form PDE**   $\varphi \frac{\partial S_{\alpha}}{\partial t} + \nabla \cdot \boldsymbol{u}_{\alpha} = B_{\alpha} \left( q_{\alpha} - \varphi S_{\alpha} \frac{\partial}{\partial t} \left( \frac{1}{B_{\alpha}} \right) - \boldsymbol{u}_{\alpha} \cdot \nabla \left( \frac{1}{B_{\alpha}} \right) \right)$  **Coefficient Form PDE**  $\boldsymbol{u}_{a} = f_{a} \boldsymbol{u} - K f_{a} \sum \lambda_{\beta} \left( (\rho_{\beta} - \rho_{\alpha}) \boldsymbol{g} \right), \quad for \mid \overline{\boldsymbol{a}} = \overline{\boldsymbol{o}, \boldsymbol{w}} \right)$ where  $G_{\lambda} = g \sum f_{\beta} \rho_{\beta}, f_{\beta} = \frac{\lambda_{\beta}}{\lambda}, \lambda_{\beta} = \frac{k_{r_{\beta}}}{\mu_{\beta}}, \lambda = \Sigma \lambda_{\beta}$ 



### **Applications on Typical Reservoir Structures**





## Primary Oil-Recovery: Solution-gas Drive Mechanism

#### **Evolution of Oil Phase Saturation**





Oil & Gas Production Rates





## Secondary Oil-Recovery: Waterflooding









## Secondary Oil-Recovery: Gas Injection

#### **Evolution of Oil Phase Saturation**



Oil & Gas Production Rates





## Conclusions

Successful representation of the physical phenomenon.

Buoyancy and gravity effects visually verified.

✓ Reliable tool for the estimation of fluids recovery.

Simulation of more complex problems in EOR processes by implementing also the appropriate PDEs.



# THANK YOU!









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**c**)