Space Charge Compensation of Negative Ion Beams

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Abstract: The transport of intense ion beams with reduced beam divergence over reasonable drift distances requires a reliable compensation of the beam space charge. In the case of negative ion beams (required in the Neutral Beam Injectors envisioned for the ITER tokamak) this background charge is provided by the accumulation of positive slow ions (mainly H$_2^+$) produced by ionization of the residual gas in the drift tube, via the reaction: 

$$H^- + H_2 \rightarrow H^+ + H_2^+ + (2 - x)e$$

(with $x = 0, 1$). Primary beam currents is about 300 A/m$^2$, so that Poisson equation has a nonlinear space charge density due to particles. In a flexible set of macros called BYPO previously developed, suitable for running under Comsol Multiphysics, the positive ion background was represented by a semi empirical model, reaching 100% space charge compensation at beam core. Here a 2D selfconsistent diffusive model of the background is introduced, implemented in Comsol Multiphysics and solved, discussing also its relation with more complex hydrodynamics models and the previous 1D models. Using postprocessing routines, the production of H$_2^+$ and other secondaries is also separately computed, finding a background positive charge roughly in agreement with this model.

Keywords: ion beams, secondary beam

1 Introduction

The propagation of a high charge ion beam (despite its space charge) inside accelerator is made possible by the curvature of the accelerating field equipotentials, so that electrodes should be carefully designed [1][2][3]. In the region after the accelerator exit, called the drift region, the so-called space charge compensation (SCC) (due to accumulation of secondary particles that are slow ions and/or electrons formed by collisions of the ion beam with gas) greatly helps the propagation of beam [4]. In most simulation codes, this is simply modeled imposing a fixed ratio $R^{sc}$ of the secondary density respect to primary beam density $N_0(x)$. Analytical studies, based only on a 1D radial model, does indeed forecast a large compensation fraction, say $R^{sc} = 1.00$ negative H$^-$ ion beams and $R^{sc} \approx 0.98$ for H$^+$ ions at typical speed $v_b = 4.4 \times 10^6$ m/s, average beam density $N_0 = 5.6 \times 10^{14}$ m$^{-3}$, beam radius $b = 6$ mm and gas pressure $p_g = 0.05$ Pa. In this paper we address the axial flow of secondary ion with two Comsol Multiphysics models; this flow may modify locally $R^{sc}$ and can consequently slightly perturb the primary beam propagation (section 2 and 3).

Some Monte Carlo simulations with electrostatic fields computed by Comsol Multiphysics here presented in section 4 shows significant fluctuations of the SCC. Finally in section 5 we recall the ad hoc model of SCC used in BYPO[2, 3] for comparison. In the literature both radial transport 1D codes [1] and Monte Carlo codes [5] are well documented for positive ions. Experimental effects of SCC were also discussed[6].

For negative ions, we can consider only two major collision process, called background ion ionization and primary beam stripping

$$H^- + H_2 \rightarrow H^- + e + H_2^+ \quad (1)$$

$$H^- + H_2 \rightarrow H^0 + e + H_2 \quad (2)$$

where we mark with an underline the fast particles that approximately maintains the $v_b$ speed. We may have the sum of these two processes in one collision. The effective collision cross section are about $\sigma_1 = 2 \times 10^{-20}$ m$^{-2}$ and $\sigma_2 = 3 \times 10^{-20}$ m$^{-2}$ (for 100 keV H$^-$) [7]. In eq. (2) electrons have about 60 eV energy, while in eq. (1) they get 10 eV energy and H$_2^+$ speed is not much greater than the gas one.
A scheme of a typical experimental situation is given in fig. 1 and 2; here we take a 2D section and show two beamlets for illustration (a vertical section of the ITER accelerator will show 80 beamlets, while the minimum beamlet number is of course one). Inside accelerator, electrodes (with grids of holes) are closer to beamlets, so they shield any other electrode; but in the large open spaces of the drift region, the potential \( V_D \) of the so-called drift tube enclosing the beamlets is important. Here by convention the drift tube is the ground, so \( V_D = 0 \) and the potential \( V_{PA} \) of the last electrode PA is to be optimized. Precisely speaking, in a 2D \( yz \)-geometry holes and tubes become channels, with a height of 1 meter in \( y \)-direction; for example 2\( R_h \) is the width of the drift channel.

Before the PA we have a strong electric field \( E_z < 0 \); this field imbues the PA holes and attracts \( H^+ \) back to the accelerator, spoiling the SCC for quite a distance; to mitigate this, we are ready to bias \( V_{PA} \) from +200 V, to repel \( H^+ \) inside the drift region. If this is not enough, we can add a repeller electrode REP after the PA.

In the experience with negative ion beam (40 mA per beamlet as planned for ITER) the SCC was generally found satisfying enough even without PA biasing[8] [9] [10]. On the other side, repeller electrodes are usually added at both ends of the drift tube for intense positive ion beam (130 mA as planned for example for IFMIF [5]) due the greater beam quality there required.

Figure 1: A scheme of the accelerator end section. In lower beam, some particle positions and velocities are put into evidence; NEU is for neutralizer. Simulation region (dashed border rectangle) is expanded in fig. 2.

2 Basic equation and simplification

Introducing a reference temperature \( T_0 = 1 \) eV, we can determine a Debye length \( \lambda_D = (e_0 T / e^2 N_0)^{1/2} \) where \( N_0 \) is the average beam density, and a sound speed \( c_s = (T_0 / m H^+_2)^{1/2} \). With the scaled density \( n = N_s / N_0 \) and the potential \( u = -e \phi / T_0 \) the Poisson equation becomes

\[
\lambda_D^2 \triangle u = n_2 - n_e - n_b = n_a \quad (3)
\]

with the shorthand \( n_2 = n H^+_2 \) and \( n_b = n H^- \).

We may assume that beam is parallel exciting PA and, for a short simulation region as shown in fig. 1 and 2, the propagating beam has no time to diverge; also we keep beam speed \( v_b \) fixed in first approximation. So we use a fixed beam density, as a flat beam profile \( n_b = \Theta(b - |x|) \) or a parabolic profile \( n_b = 1.5 \max(0, 1 - (x/b)^2) \).

In this first model electron density is neglected both for simplicity and for the following justifications. For the greater thermal speed of electron, \( n_e \) is expect to be order of one % of \( n_2 \). Even if the electron density is known to be important for instability suppression[9], if a stationary model would prove that \( H^+_2 \) may accumulate to compensate \( n_b \) fully, it is reasonable to expect that also \( n_b + n_e \) can be similarly compensated.

The slow ion conservation equation is

\[
\text{div}(n_2 \mathbf{v}) = n_b / \lambda_g \quad (4)
\]

where \( \mathbf{v} \) is the average ion velocity (divided by \( c_s \)) and \( \lambda_g = c_s / (N_g \sigma_{ei} v_b) \) is reference length typical of SCC; here \( N_g = 1.2 \times 10^{19} \) m\(^3\) the gas density. The momentum conservation takes the form

\[
\mu (\mathbf{v} \cdot \nabla) \mathbf{v} = \nabla u - \frac{\nabla p}{n_2 T_0} - \frac{\mathbf{v}}{\lambda_2} + R_e \frac{n_b \mathbf{v}}{n_2 \lambda_g} \quad (5)
\]

where \( \mu = 1 \) to maintain the convective term, \( p \) is the pressure, \( \lambda_2 \) is the mean free
path, determined from (nearly) elastic collisions of H_3^+ with other particles, and R_e are the other effects (if any) of those collisions; the last term expresses the fact that ions are produced by eq. [11] at rest and this decreases the average speed \[ \text{[11]} \]. It should be noted that this continuous generation of ions spreads the distribution of velocities (still different from a maxwellian); [so a free-fall model would be a possible choice, but it seems affordable in 1D radial calculations at most \[ \text{[11]} \]. Moreover this spread is the origin of the pressure p, given by a separated balance equation in principle. Here we close the equations by assuming \( p = n_T e \).

The mean free path estimate \( \lambda_2 \) also includes the reaction

\[
H_3^+ + H_2 \rightarrow H^0 + H_3^+ \quad (6)
\]
since a H_3^+ will be transported similarly to a H_3^+ ion; its cross section is \( \sigma_3 = 1.9 \times 10^{-19} \text{m}^2 \) at \( T_0 = 1 \text{eV} \). In comparison the elastic cross section is \( \sigma_4 = 1.3 \times 10^{-19} \text{m}^2 \) \[ \text{[12]} \].

The Coulomb collisions between H^- primary were studied too, also because they may heat the ions; both collision rate and heat transfer rate (computed with the classical theory \[ \text{[13]} \]) are anyway fully negligible.

### 2.1 The diffusion model

It can be argued that, when the beam space charge is fully neutralized, the electric field is small and slowly changing inside the core of the drift region space (the dashed ellipse in fig 2) so that \( v \) is small and the convective term can be dropped in eq. [3]. Formally this amount to put \( \mu = 0 \); after defining an effective free path \( \lambda_0 \) we solve for \( v \) as

\[
\lambda_0^{-1} = \lambda_2^{-1} + (n_b/n_2\lambda_g) \quad (7)
\]

\[
v = \lambda_0 \nabla(u - \log n_2) \quad (8)
\]

Substituting this in eq. [4] we get the

\[
\text{div}\{\lambda_0 n_2 \nabla u - \lambda_0 \nabla n_2}\} = n_b/\lambda_g \quad (9)
\]

where inside the divergence operator we recognize the usual current given by the Fick’s law (mobility+diffusion terms).

### 2.2 Boundary condition (bc)

Our simulation region has a very limited extension in x direction: \(|x| \leq L_x/2\), where \( L_x \) is the spacing of the holes in a multiperture electrodes; in other words, our simulation domain is the region common both to a single beamlet system and a many beamlet system. By a proper choice of bc at lower and upper boundaries we can approximately simulate both systems, also economizing problem memory size. For the single beamlet case, we know that there is a wall with \( u = 0 \) at a distance \( w = R_t - 0.5L_x \) (in planar geometry) from our boundary; by a series expansion in \( w \) we approximate \( u \) at wall with \( u + \mathbf{n} \cdot \nabla u \) at boundary, and set this value to zero; here \( \mathbf{n} \) is the outward normal. Introducing \( i_w = 1/w \) we finally write

\[
\mathbf{n} \cdot \nabla u = -i_w u \quad \text{at} \quad x = \frac{1}{2} L_x \quad (10)
\]

For the case of an infinite array of beamlets, we have symmetry at upper and lower boundaries, so that bc is eq. [10] with \( i_w = 0 \). At the exit plane \( z = z_1 \) (in the middle of an open space like the drift tube) we assume again a simple Neumann condition. Of course at the PA we have a fixed potential \( u = u_{PA} \). At the beam input plane \( z = z_2 \) we can assume that \( u_z(z_2, x) \) is known by simulations on larger scales. In particular, if we imagine that the PA hole extends even for \( z < z_2 \) or that \( z_2 \) is in the middle of the PA hole, we conclude that beam space charge is symmetric around \( z_2 \) and does not contribute to \( u_z \), the z-derivative of \( u \). The lower mode of the remaining Laplace equation is \( u = c_1 \exp(-k_0 z) \cos(k_0 x) \) with \( c_1 \) a constant and \( k_0 = \pi/(2a) \) where \( 2a \) is the entrance channel width. In summary

\[
u_z(z_2, x) = u_1 \cos(k_0 x) \quad (11)
\]

where \( u_1 \) is a parameter assigned by the user. The condition for density \( n_2 \) approximately follows from considering \( \lambda_0 n_2 \nabla u \) as a convective flow (and \(-\lambda_0 \nabla n_2 \) as the diffusive flow). When ions hits the PA, they immediately become neutral, so no ion can diffuse back: convective flow has no restriction and diffusive flow is zero, that is

\[
\mathbf{n} \cdot \nabla n_2 = 0 \quad (12)
\]

At the exit plane, \( n_2 z = 0 \) if we want to obtain an equilibrium, so we can still impose eq. [12] Finally at the upper and lower boundary we can have a partial recirculation of ions from one beamlet to another: precisely assume that a fraction \( R_e \) of the ions
that exit (if any) diffuses back. So

\[ \mathbf{n} \cdot \nabla n_2 = \max(0, R_c n_2 \mathbf{n} \cdot \nabla u) \] (13)

Even in the many beamlet case we guess \( R_c \leq 0.5 \). It is indeed not realistic to take \( R_c = 1 \) since ions escaping from one beamlet may as well pass through beamlets and arrive to the drift tube wall. In the case of a single beamlet the recirculation fraction \( R_c \) is zero, so that eq. [13] becomes eq. [12].

Figure 3: Map of the normalized ion density \( n_2 \), to enhance graph visibility, we plot the decimal log, with a minimum displayed \( n_2 \) of 0.001

Figure 4: Plot of \( \int dx \, n_2(z, x) / \int n_b \)

Figure 5: Map of the normalized charge \( n_a \)

Figure 6: Map of the normalized potential \( u \)

Figure 7: The normalized potential \( u(z, x) \) for \( x = 0, 2, 4, 6 \) and 8 mm; the first two lines are superposed (green); the last line (magenta) touch the PA visibly

Figure 8: Plots of end potential \( u_h = u(z_h, 0) \) vs PA potential \( u_{PA} \); also shown current of \( \text{H}_2^+ \) crossing \( z = 0 \) plane (\( y \) extension= 1m).

## 3 Results

It is well known that eqs. 3-5 system is not suitable for nonlinear solvers, unless proper stabilization schemes are adopted \[14, 15\]. So we thus use the reduced system of eqs. 3 and 9 for a preliminary modelling (with \( n_2 = 1 \) in eq. 7). Here we restrict to the single beamlet case, so \( R_c = 0 \) and we take \( i_w = 25 \text{ m}^{-1} \) (corresponding to drift channel width of 102 mm). Other dimensions are given in fig 2. We set \( u_{PA} = -25 \) and a modest field inside PA: \( u_1 = 10^3 \text{/ m} \).

The more novel result noted is the distribution of \( \text{H}_2^+ \) ions shown in Fig 3. A cloud of \( \text{H}_2^+ \) ions extends also outside the beam. To obtain a nearly zero potential \( u(z, 0) \) from eq. 3 is necessary that the total charge \( n_a \) integrated on all \( x \) is near to zero, and indeed we see this compensation in fig 8. The existence of \( \text{H}_2^+ \) outside the beam so implies that inside the beam, especially near borders, we have a local space charge compensation less than 100 % (see the yellow lines in fig 5).

Potential \( u \) is shown in figs 9 and 7 in this case axial compensation settles very
rapidly, so the only regions where we find a large electric field is the PA hole; there we found the largest unbalance of the total space charge \( n_a \) (see fig 5) according to Poisson equation. It is interesting to plot the net current of \( H^+ \) (exiting from or falling inside the PA channel, at \( z = 0 \)) and the end axis potential \( u_h = u(za, 0) \) against the \( u_{PA} \); see in Fig 8. For the modest \( u_1 \), any \( u_{PA} \leq -20 \) V suffices to keep back streaming under 30\( \mu \) A; in that range, \( u_h \) is nearly constant and about \(-7\).

4 Monte Carlo models

Even if computationally much more intensive than previous fluid models, PIC-MC (Particle In Cell-Monte Carlo) simulations are the standard choice\[5, 16\] because they are simpler to define and they naturally follow the time evolution of the system; in particular they verify whether SCC stationary equilibrium is stable or not. For this reasons, we also develop a MC tool: starting from an assigned space charge distribution \( n_0^a \), the electric field is computed by the Comsol Multiphysics solver for Poisson equation. Then new particles are generated continuously according to eq. 1; new particles (and the old ones if any) are advanced with a leap-frog method for a given number \( N_s \) (typically 1) of time steps \( dt \). After, space charge is updated, Poisson equation is solved again, and time evolution is resumed. Also the \( H^- \) beam trajectories can be updated after a longer period \( dt_2 \), with a call to the ‘postplot’ routine of Comsol Multiphysics.

The particles involved have quite different velocities, that is, \( v_b \) for \( H^- \) and 
\[v_2 = \left(\frac{2T_g}{m_{H^+}}\right)^{1/2} \text{ with } T_g = 0.025 \text{ eV}\]
the gas temperature at start; similarly \( v_e = \left(\frac{2T_e}{m_e}\right)^{1/2} \) for electrons with \( T_e = 10 \text{ eV}.\)

We get \( v_b \approx 10^6 \text{ m/s} \) and \( v_2 \approx 10^3 \text{ m/s}.\)

To follow the dynamics of the whole systems we should choose the characteristic time step \( dt \) of our simulation. So, according to electron velocity and Debye length we obtain \( dt \approx \frac{\lambda_D}{v_e} \approx 1.7 \times 10^{-10} \text{ s}; \) scaling to a lower density beam \( n_0 = 10^{13} \text{ m}^{-3}, \) we can use \( dt \approx 10^{-9} \text{ s}.\)

The secondary production is
\[R_s = d N_2 / dt = N_g n_0 \eta(x) \sigma_1 \quad (14)\]

![Figure 9: Evolution of \( \phi(t)/\phi(t=0) \) at central axis point \( z = L_z/2 \), and of normalized particles densities vs time index \( t/dt \).](image)

![Figure 10: Potential well depth \( \phi(L_z/2, 0) \) vs time index \( t/dt \).](image)

![Figure 11: Flux oh \( H^+ \) leaving the domain vs time. Red line: radial flux, Blue line: axial flux. Electrons behavior is similar.](image)

So that an effective density of secondary \( n_s = R_s \ dt \) is created at each time step, and divided into an suitable number of macro-particles whose positions are chosen randomly inside the beam region with a velocity depending on particles species.
4.1 Monte Carlo results

The drift length $L_z = 0.5$ m is longer than in the fluid simulations and the PA hole region is omitted, setting $u_1 = 0$ in eq 11. Lateral boundary conditions are as for a single beamlet, that is, eq 10.

In a first series of simulation, secondary charge was zero at start, that is $n^0_a = -n_b$. This gives a huge potential well (negative for potential $\varphi$) so that beam opens up at a first time until SCC is enough to significantly reduce this potential well; after that beam can propagate with minor perturbation.

Beam reflection was also observed with dense beam. Due to the many time scales involved, some time oscillation may appear (and eventually damp): generally, ion losses oscillate between axial and radial directions; electron losses roughly have the opposite phase.

The potential is expected to have a maximum depth at the central point $x = L_z/2$ and $z = 0$; let $\phi_R$ be the ratio of this potential depth and its value at $t = 0$. Figure 9 shows time evolution of $\phi_R$ and of the normalized particle densities. This depth is drastically reduced by the accumulation of $H^+_2$ ions, and the neutralization is reached in a time $\tau_n = 9 \times 10^{-9}$ s close to the theoretical SCC time defined as $\tau = 1/(\sigma_1 * N_g * v_b) = 6.3 \times 10^{-9}$ s. Electron apparently do not play a role in the transient phase of compensation, since they are fastly expelled from the beam.

In a second series of simulations, to better analyze whether the SCC is stable or not, the transient phase of the SCC was shortened by starting with a neutralization degree of 99.9%. Picture 10 shows the value of the potential depth $\phi(L_z/2, 0)$. An oscillating potential is found, reflecting the way the beams adjust for maintaining its degree of neutralization: secondaries are expelled or accumulated depending on their charge and the potential oscillates between the points of maximum accumulation of both species.

Compared to the beam accelerating voltages of 100 kV the amplitudes of these oscillations are relatively small, and tend to decrease in time; their effect on beam optic is negligible and the SCC appear basically stable. Picture 10 shows the fluxes of $H^+_2$ ions expelled from the beam and leaving the domain in the axial or radial direction. Obviously the two quantities are correlated on beam potential: ions leave the domain radially especially during the $H^+_2$ accumulating phase ($\phi < 0$) while, when potential becomes positive they are expelled axially, gaining an acceleration proportional to potential. Electrons follow a similar dynamics with opposite phase. So, in spite of the qualitative results of this simulation, an important topic was pointed out thanks to the 2D geometry: due to the fact that the radial potential is very small compared to the axial one, particles are expelled from the beam in all directions, meaning the dynamic of the phenomena is not simply radial, as previously supposed.

5 Comparison with Bypo

An important new feature of the code BYPO which addresses the whole 2D geometry of
the accelerator column was a model for the SCC (see figure [12]); anyway the simulated span of the drift region is rather short (2 cm). For this reason an ad hoc model, tunable to follow results of more detailed models, was inserted into BYPO. In current notation

\[ n_2 = R_{2c}^n \Theta(u_e)(u-u_h)/T_2 \]

\[ n_e = R_{e}^n 2/(1+e^{(u-u_h)/T_e}) \]  

where end potential \( u_h \) is iteratively adjusted from BYPO, \( R_{2c}^n \) and \( R_{e}^n \) are the assigned fraction of density of \( \text{H}_2^+ \) and electrons at point \( (z_h,0) \) with respect to average beam density as computed by a 1D analytical model[1]. In our case \( R_{2c}^n = 0.9986 \) and \( R_{e}^n = 0.0023 \). Similarly \( T_2 \) and \( T_e \) are the assigned ion and electron temperature (divided by \( T_0 \)); here \( T_e = 12.0 \) from that analytic model[1] and \( T_2 = 0.8 \) as an user guess. For \( \text{H}_2^+ \) a maxwellian distribution was used, which is not invalid where ions are confined; indeed the Heaviside function \( \Theta \) has the purpose to limit \( n_2 \) to region where the ion are axially confined. This agrees to intuitive expectations and as saw it is not exactly confirmed by our 2D model.

It should be noted that even if equipotential found are in reasonable agreement with the model section 2 and 3, BYPO space charge looks correct only on the average, with some fluctuation apparent. The advantage of more detail diffusive model over simpler local model like eq. [15] is thus evident.

References


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